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# CCITT 

## THE INTERNATIONAL

TELEGRAPH AND TELEPHONE
consultative committee

## RED BOOK

# FUNCTIONAL SPECIFICATION AND DESCRIPTION LANGUAGE (SDL) 

RECOMMENDATIONS Z.100-Z. 104

## VIIITH PLENARY ASSEMBLY

MALAGA-TORREMOLINOS, 8-19 OCTOBER 1984

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## CONTENTS OF THE CCITT BOOK APPLICABLE AFTER THE EIGHTH PLENARY ASSEMBLY (1984)

## RED BOOK

Volume I - Minutes and reports of the Plenary Assembly. Opinions and Resolutions.

Recommendations on:

- the organization and working procedures of the CCITT (Series A);
- means of expression (Series B);
- general telecommunication statistics (Series C).

List of Study Groups and Questions under study.

| Volume II | - (5 fascicles, sold separately) |
| :---: | :---: |
| FASCICLE II. 1 | - General tariff principles - Charging and accounting in international telecommunications services. Series D Recommendations (Study Group III). |
| FASCICLE II. 2 | $\begin{aligned} & \text { - International telephone service - Operation. Recommendations E.100-E. } 323 \text { (Study } \\ & \text { Group II). } \end{aligned}$ |
| FASCICLE II. 3 | - International telephone service - Network management - Traffic engineering. Recommendations E. 401 -E. 600 (Study Group II). |
| FASCICLE II. 4 | - Telegraph Services - Operations and Quality of Service. Recommendations F.1-F. 150 (Study Group I). |
| FASCICLE II. 5 | - Telematic Services - Operations and Quality of Service. Recommendations F.160-F. 350 (Study Group I). |

Volume III - (5 fascicles, sold separately)
FASCICLE III. 1 - General characteristics of international telephone connections and circuits. Recommendations G.101-G. 181 Study Groups XV, XVI and CMBD).

FASCICLE III. 2 - International analogue carrier systems. Transmission media - characteristics. Recommendations G.211-G. 652 (Study Group XV and CMBD).

FASCICLE III. 3 - Digital networks - transmission systems and multiplexing equipments. Recommendations G. 700 -G. 956 (Study Groups XV and XVIII).

FASCICLE III. 4 - Line transmission of non telephone signals. Transmission of sound-programme and television signals. Series H, J Recommendations (Study Group XV).

FASCICLE III. 5 - Integrated Services Digital Network (ISDN). Series I Recommendations (Study Group XVIII).

FASCICLE IV. 1 - Maintenance; general principles, international transmission systems, international telephone circuits. Recommendations M.10-M. 762 (Study Group IV).

FASCICLE IV. 2 - Maintenance; international voice frequency telegraphy and fascimile, international leased circuits. Recommendations M.800-M. 1375 (Study Group IV).

FASCICLE IV. 3 - Maintenance; international sound programme and television transmission circuits. Series N Recommendations (Study Group IV).

FASCICLE IV. 4 - Specifications of measuring equipment. Series 0 Recommendations (Study Group IV).

Volume V - Telephone transmission quality. Series P Recommendations (Study Group XII).

Volume VI - ( 13 fascicles, sold separately)

FASCICLE VI. 1 - General Recommendations on telephone switching and signalling. Interface with the maritime mobile service and the land mobile services. Recommendations Q.1-Q. 118 bis (Study Group XI).

FASCICLE VI. 2 - Specifications of Signalling Systems Nos. 4 and 5. Recommendations Q.120-Q. 180 (Study Group XI).

FASCICLE VI. 3 - Specifications of Signalling System No. 6. Recommendations Q.251-Q. 300 (Study Group XI).

FASCICLE VI. 4 - Specifications of Signalling Systems R1 and R2. Recommendations Q.310-Q. 490 (Study Group XI).

FASCICLE VI. 5 - Digital transit exchanges in integrated digital networks and mixed analogue-digital networks. Digital local and combined exchanges. Recommendations Q.501-Q. 517 (Study Group XI).

FASCICLE VI. 6 - Interworking of signalling systems. Recommendations Q.601-Q. 685 (Study Group XI).

FASCICLE VI. 7 - Specifications of Signalling System No. 7. Recommendations Q.701-Q. 714 (Study Group XI).

FASCICLE VI. 8 - Specifications of Signalling System No. 7. Recommendations Q.721-Q. 795 (Study Group XI).

FASCICLE VI.9 - Digital access signalling system. Recommendations Q.920-Q. 931 (Study Group XI).

FASCICLE VI. 10 - Functional Specification and Description Language (SDL). Recommendations Z.101-Z.104 (Study Group XI).

FASCICLE VI. 11 - Functional Specification and Description Language (SDL), annexes to Recommendations Z.101-Z. 104 (Study Group XI).

FASCICLE VI. 12 - CCITT High Level Language (CHILL). Recommendation Z. 200 (Study Group XI).

FASCICLE VI. 13 - Man-Machine Language (MML). Recommendations Z:301-Z. 341 (Study Group XI).

Volume VII - (3 fascicles, sold separately)
FASCICLE VII. 1 - Telegraph transmission. Series R Recommendations (Study Group IX). Telegraph services terminal equipment. Series $S$ Recommendations (Study Group IX).

FASCICLE VII. 2 - Telegraph switching. Series U Recommendations (Study Group IX).
FASCICLE VII. 3 - Terminal equipment and protocols for telematic services. Series $T$ Recommendations (Study Group VIII).

Volume VIII - (7 fascicles, sold separately)
FASCICLE VIII. 1 - Data communication over the telephone network. Series V Recommendations (Study Group XVII).

FASCICLE VIII. 2 - Data communication networks: services and facilities. Recommendations X.1-X. 15 (Study Group VII).

FASCICLE VIII. 3 - Data communication networks: interfaces. Recommendations X.20-X. 32 (Study Group VII).

FASCICLE VIII. 4 - Data communication networks: transmission, signalling and switching, network aspects, maintenance and administrative arrangements. Recommendations X.40-X. 181 (Study Group VII).

FASCICLE VIII. 5 - Data communication networks: Open Systems Interconnection (OSI), system description techniques. Recommendations X.200-X. 250 (Study Group VII).

FASCICLE VIII. 6 - Data communication networks: interworking between networks, mobile data transmission systems. Recommendations X.300-X. 353 (Study Group VII).

FASCICLE VIII. 7 - Data communication networks: message handling systems. Recommendations X.400-X. 430 (Study Group VII).

Volume IX - Protection against interference. Series K Recommendations (Study Group V). Construction, installation and protection of cable, and other elements of outside plant. Series L Recommendations (Study Group VI).

Volume X - (2 fascicles, sold separately)
FASCICLE X. 1 - Terms and definitions.
FASCICLE X. 2 - Index of the Red Book.

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# TABLE OF CONTENTS OF FASCICLE VI. 10 OF THE RED BOOK 

## Recommendations Z. 100 to Z. 104

Functional specification and
description language (SDL)
Rec. No. Page
Z. 100 Introduction to SDL ..... 3
Z. 101 Basic SDL ..... 16
Z. 102 Structural concepts in SDL ..... 47
Z. 103 Functional extensions to SDL ..... 64
Z. 104 Data in SDL ..... 105

## PRELIMINARY NOTES

1 The Questions entrusted to each Study Group for the Study Period 1985-1988 can be found in Contribution No. 1 to that Study Group.

2 In this Fascicle, the expression "Administration" is used for shortness to indicate both a telecommunication Administration and a recognized private operating agency.

# FASCICLE VI. 10 

Recommendations Z. 100 to Z. 104

## FUNCTIONAL SPECIFICATION AND DESCRIPTION LANGUAGE (SDL)

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## INTRODUCTION TO SDL

## Introduction

This Recommendation is a general explanation of and introduction to the CCITT Specification and Description Language (SDL). The language is defined in detail in Recommendations Z. 101 to Z.104.

### 1.1 General

The purpose of recommending SDL is to provide a language for unambiguous specification and description of the behaviour of telecommunications systems. The specifications and descriptions using SDL are intended to be formal in the sense that it is possible to analyse and interpret them unambiguously.

A system specification consists of a specification of the functional behaviour and a set of general parameters of the system. SDL aims only to describe the behavioural aspects of a system; the general parameters describe properties like capacity and weight which have to be described using different techniques.

The terms specification and description are used with the following meaning:

- a specification of a system is the description of its required behaviour, and
- a description of a system is the description of its actual behaviour.

SDL describes the behaviour in a stimulus/response fashion, assuming that both the stimuli and responses are discrete entities. The approach is based on the concepts of extended finite state machines.

The behaviour of the system as described in SDL is the sequence of responses to any given sequence of stimuli as seen from outside the system. Any two systems described in SDL having the same behaviour in this respect are said to be functionally equivalent. The concept of functional equivalence is used to compare systems with each other, e.g. a specification of a required system with a description of an offered system. The SDL User Guidelines, which are appended to the Recommendations contain a discussion on the criteria and methods for this comparison.

SDL also provides structuring concepts which allow a system to be partitioned so that it can be defined, developed and understood one part at a time.

These concepts are of value both initially in specifying a system, when different aspects can be independently dealt with, and later in describing a system, when the description structures should match the system structure.

### 1.2 Objectives

The general objectives when defining SDL have been to provide a language that:

- is easy to learn, use and interpret in relation to the needs of an operating organization;
- provides unambiguous specifications and descriptions for ordering and tendering;
- may be extended to cover new developments;
- is able to support several methodologies of system specification and design, without assuming any one of these.


### 1.3 Scope

The main area of application for SDL is the description of the behaviour of aspects of telecommunications systems. Applications include:

- call processing (e.g. call handling, telephony signalling, metering) in SPC switching systems;
- maintenance and fault treatment (e.g. alarms, automatic fault clearance, routine tests) in general telecommunications systems;
- system control (e.g. overload control, modification and extension procedures);
- data communication protocols.

SDL can of course also be used for the description of any behaviour capable of being described using a discrete model, i.e. communicating with its environment by discrete messages.

The following survey of SDL is intended as an introduction to Recommendations Z. 101 to Z.104. The explanations given here are, except for $\S 2.1$, not formal definitions, but are intended as just tutorial explanations.

### 2.1 Some basic definitions

Some general concepts and conventions are used throughout Recommendations Z.100 to Z.104. Their definitions follow here:

Type, definition and instance

In the Recommendations, an entity is strictly separated from its definition. The schema and terminology defined below and shown in Figure 1/Z. 100 are used.


FIGURE 1/Z. 100
The Type concept

A type is defined by its definition, which defines all properties associated with that type. A type may be instantiated in any number of instances. Any instance of a particular type, has all the properties defined for the type.

The schema applies to several SDL concepts, e.g. we have system definitions and system instances, process definitions and process instances.

The instances of a type may be types themselves. The properties associated with types are inherited according to the hierarchical application, e.g. the properties of the generic type system are inherited by all instances of specific system definitions.

To avoid cumbersome text, the convention used is that whenever it is obvious from context that the definition or the instance of a type is meant the attribute is omitted.

## Names

The following naming conventions and terminology are adopted to identify definitions and instances:
All identifiers used in a representation are unique. The identification of an entity consists of two parts: one name part and one qualifying part:

$\underbrace{$|  <System name $>$ |
| :---: |
|  <Signal type $>$ |}$_{\text {Qualifying part }}$

The qualifying part is derived from the complete hierarchical context the entity is defined in and the type of the entity. The name part should be a meaningful name in relation to the purpose or effect of the named entity.

When the identification appears in the concrete syntax, the obvious qualifiers may be implied only; i.e. when it is not ambiguous only the name part should be used.

## Visibility rules

When an identifier is introduced into a specification or description that identifier is visible at the point of introduction and at levels directly below the point of introduction in the specification or description hierarchy. The highest level at which the identifier is visible is indicated by the lowest hierarchical level given in the qualifying part of the identifier.

## Specification error

Where properties of an SDL specification are inconsistent or ambiguous, that specification is invalid. Where the interpretation of an SDL specification violates properties of a specification which is valid, that system interpretation is in error. An interpretation of a system which leads to an error means that the future behaviour of the system cannot be predicted from the specification.

## 2.2 <br> The basic SDL

The dynamic behaviour of an SDL system is generated by process instances, acting concurrently. A process is modelled as an extended finite state machine. It will only act in response to external discrete stimuli, and may then generate discrete responses back to its environment. Other processes may accept the generated responses as stimuli.

In SDL a process will wait in a state until it receives a valid signal from its environment. Then it will perform a transition to another state. During the transition it may perform actions; these may either be manipulation of information local to the process or sending signals to other processes or to the external environment of the system.

All processes in a system or in its environment have access to the "absolute time", and may perform time measurements and timing.

Process instances may be created and terminated dynamically. Any instance 4 may be created by another instance or it may exist at system initialization time. A process instance may only be terminated by an explicit stop action performed by itself.

Several signal instances may be waiting to be accepted by a process. In order to handle this signal queue, an input port is associated with each process instance. The queueing discipline is basically first in first out, but the process may itself manipulate this by a save-signal-set associated with a state.


FIGURE 2/Z.100

## A process definition

Signal instances may carry data values, which will be available to the receiving process instance when the signal is received. The data values may be stored in, and retrieved from, local variables of the process.

The static structure of an SDL system is described in terms of a system, blocks and channels, as shown in Figure 3/Z.100.


FIGURE 3/Z. 100
Static structure of an SDL system

The system is a composition of blocks, connected to eachother and to the system boundary via channels. The system boundary separates the system from its environment. The environment is assumed to "behave in an SDL-like manner"; i.e. it will send signals to the system and accept responses in the form of signals from the system.

The channels act as the transport media for signals between blocks and between blocks and the system boundary. Channels are unidirectional. The blocks are containers for the processes, and serve to structure the system in building blocks.

### 2.3 Data in SDL

SDL processes may retain and manipulate data values. The data values are bound to variables, which are local to a process. However, data values may be sent between processes, and to and from the environment, by means of signals. Local variables for a process are defined in the process definition.

The data treated is typed. A number of predefined data types are defined in SDL. In addition the user may define new data types. The predefined data types are:

- Boolean having the values TRUE and FALSE and the normal logical operations on these values.
- Integer having its normal mathematical meaning.
- Natural having the normal mathematical meaning of natural numbers.
- Real having the normal mathematical meaning of real numbers.
- Character having the normal (as in programming languages) meaning and having the values and representation as in the CCITT alphabet number 5.
- Array an indexed collection of items which are all of the same data type. This is an extension of the normal meaning of array as used in programming languages.
- Structure a composition of a number of data types which may be different from one another.
- String a list of items of any data type and of arbitrary length.
- Charstring a list of characters of arbitrary length. Note a charstring is a string of characters formed from the data type string with the data type character.
- Powerset having the normal mathematical meaning such that a powerset value is an ordered set.
- PId used to identify process instances.
- Time absolute time.
- Duration the interval between two instants in absolute time.
- Timer the data type used for timers and which defines the operations SET and RESET for TIMER variables.

The STRUCT concept allows further data types containing composite values composed from a number of (possibly different) data types to be constructed.

The user-defined data types may be defined in terms of the predefined data types together with restrictions like range of an integer, or they may be additional abstract data types. Abstract data types are defined using an "axiomatic" method.

Data types may be generic for a system, or contained in a block definition, a channel definition or in a process definition. The definition is visible, and thus usable, within the scope of the object they are contained in. e.g. If a type definition is contained in a block, data items of that type may be used in all processes contained in the block and in the sub-blocks of the block.

### 2.4 Structural concepts in SDL

Structural concepts are provided in SDL in order to facilitate descriptions of complex and/or large systems. The concepts are so defined that they can support:

- the partitioning of large descriptions into modules so that parts can be dealt with and understood independently;
- the description of a system, or parts of a system, on several levels of abstraction;
- the description of the actual structure of a system.

When using these structural concepts it should be made clear if they represent the required or actual structure, or are just used to facilitate the representation.

In the basic SDL, a system is composed of blocks, channels and processes. These components may be further structured, i.e. blocks into sub-blocks and sub-channels, channels into blocks and channels, and processes into sub-processes. A process definition may also be further detailed in a number of steps by using procedures and macros.

When partitioning blocks into sub-blocks and sub-channels a hierarchical multi-level description of the system is obtained. The information contained in the upper levels should be contained in the interfaces of the lower levels. The obtained structure may be illustrated by a block tree diagram as shown in Figure 4/Z.100.


FIGURE 4/Z. 100
A block tree diagram

It may also be described in more detail by a block interaction diagram as shown in Figure 5/Z.100.


FIGURE 5/Z. 100

A block interaction diagram

This latter diagram also shows the channels and sub-channels connecting the structure of blocks and sub-blocks. Using this block partitioning, it is only necessary, for the description to be meaningful, that the most detailed sub-blocks (the "leaf-blocks" in the block tree diagram) contain processes.

Partitioning of channels into channels and blocks will also result in a hierarchical structure. A simple example is given in Figure 6/Z.100.

a) A system that is not partitioned


FIGURE 6/Z. 100

## Channel partitioning

The partitioning of a process into a set of sub-processes is related to block partitioning, as the sub-processes of a process must always be located in the sub-block(s) of the block containing the process. This is shown in Figure 7/Z. 100.


FIGURE 7/Z. 100

## Process partitioning

The sub-processes of a process represent together an alternative, more detailed, description of the behaviour described by the process. Thus when having a description as in Figure 7/Z.100, a choice has to be made if the detailed behaviour, represented by the sub-processes, or the less detailed one, represented by the process, should be interpreted. In SDL the alternative descriptions are said to support different levels of abstraction.

The partitioning of a process is illustrated by a process tree diagram as shown in Figure 8/Z.100.


FIGURE 8/Z. 100

## A process tree diagram

A process may also be structured and detailed by the use of procedures. A procedure in SDL is similar to procedures in programming languages. It represents a parameterised and predefined behaviour which may be invoked by any process having access to its definition. The procedures may be predefined in libraries, or user-defined.

A procedure is defined as a set of actions and may include states, in a similar manner to a process. An example of the use of procedures is shown in Figure 9/Z.100.


FIGURE 9/Z. 100

## Example of use of procedures in a transition

SDL representations may also be structured by the use of macros. A macro is a syntactical means to ease the drawing/writing of SDL representations, and to ease the understanding of them. A macro is a named collection of syntactical items, defined by the user. Whenever a reference to a macro appears in a description, it can be understood by replacing it with the items it is defined as, i.e. it has no semantics of its own. Macros may be used in any SDL representation, e.g. for process representations, for structural diagrams, etc. An example of the use of a macro is shown in Figure 10/Z.100.


FIGURE 10/Z. 100

Example of the use of a macro

All the structuring concepts in SDL may of course be used in combination with each other.

Composite operations in SDL are standard shorthand notations provided in the language to simplify the design of SDL processes. They are defined in terms of other SDL operations, and should be interpreted as if they were replaced by those operations.

Normally, the composite operations imply hidden states and signal interchange with other processes, which is why sometimes care should be taken of side effects.

The composite operations provided are:
Import/Export of data values
A shorthand notation for accessing values of data items local to the other processes via an implied signal interchange.

## Enabling condition

A shorthand notation for the capacity either to accept a signal as an input or to save the signal depending on a condition, which may contain imported values. This is modelled as having several states in which the signal is accepted as input and other in which the signal is saved. The implied state is chosen after evaluation of the condition. The operation may also imply signal interchange.

## Continuous signals

A shorthand notation for leaving a state and entering a transition when a condition, which may use imported values, becomes true. A continuous signal has lower priority than "normal" signals, and may be used to stimulate a transition when an external data value changes. The operation implies a number of states and signal interworking.

By using composite operations, the number of states and transitions in a process definition may be reduced.

The concept of option in SDL

When several similar applications are specified or described by using SDL often the same process definition may be applicable in several applications if only slightly modified. The OPTION concept makes it possible to have optional parts in a process definition.

Also, in a specification, it allows the representation of equally acceptable behaviours from the specifier's viewpoint. The actual system will implement one of these alternatives.

## 3 Preliminaries to the language specification

The language specification of SDL is contained in Recommendations Z.101, Z.102, Z.103 and Z.104. In the following preliminaries the methods and strategies used when defining the language are explained and guidelines on how to read the Recommendations are given.

### 3.1 Strategy used in the language specification

SDL gives a choice of two different syntactic forms to use when representing SDL descriptions; a Graphic Representation (SDL/GR), and a textual Phrase Representation (SDL/PR). As they both are concrete representations of the same SDL semantics, they are equivalent from a semantic point of view. In order to ensure that they are equivalent to each other, and thus transformable into each other, the definition of the semantics of SDL is strictly separated from the definitions of the different concrete syntaxes. The relations between the semantics definition of SDL and the concrete syntactical forms may be represented as shown in Figure 11/Z.100.

The semantics of SDL are defined by using an abstract syntax, with no concrete representation, associated with rules for well-formedness and interpretation. This definition is called the Common Language Model. Each of the concrete syntactical forms have then a definition of its own syntactical form and of its relationship to the abstract syntax (i.e. how to transform into the abstract form). Using this approach there is only one definition of the semantics of SDL; each of the concrete representation forms will inherit the semantics via its relations to the abstract syntax. The approach also ensures that the concrete syntactical forms are equivalent. As the transformations work both ways, either representation may be transformed into the other form via the abstract syntax.


FIGURE 11/Z. 100

## Structure of SDL language specifications

The interpretation rules of the common language model are defined in an operational manner. i.e. The definition describes how instances of SDL concepts interpret their definition as an "abstract SDL machine". In addition, a mathematical definition of SDL in denotational semantics is also provided (but is not part of the Recommendations). The mathematical definition is closely related to the abstract syntax and structure of the common language model.

Following this strategy in Recommendations there will be, for each SDL concept, first a definition of the abstract syntax and its rules, then the rules of how to interpret the concept. Finally, the concrete syntactical forms to represent the concept will be given.

### 3.2 Terminology

In the Recommendations, for each SDL concept, the same term will be used consistently throughout. To distinguish occasions when a term refers to an SDL concept from those when a more general sense is meant all SDL concept terms will be in italics.

A glossary of all SDL terms is appended to the Recommendations as Annex A. The glossary contains a short explanation of each term, and a reference to where it is defined.

### 3.3 Definition of the $S D L / G R$

The SDL/GR is defined following the schema below:

- First the shape and content of the symbols are defined.
- Connectivity rules follow, when appropriate, i.e. what compositions of symbols are allowed.
- Lastly, the relations to the abstract syntax of the common language model are given.


### 3.4 Definition of the $S D L / P R$

The $S D L / P R$ is defined using syntax diagrams and additional rules in natural language. The definitions follow the schema below:

- First the syntax is defined by diagrams and text.
- Then the relations to the abstract syntax of the common language model are given.


### 3.4.1 Syntax Diagrams

A syntax diagram consists of terminal and non-terminal symbols connected by flow lines.
A terminal symbol contains a character or a sequence of characters, and the generation rules are that when passed in a path those characters should appear in the $S D L / P R$ text.

A non-terminal symbol is a reference to another syntax diagram, having the name appearing in the symbol. The generation rules are that when a non-terminal symbol appears in a diagram, the path leads into the referenced diagram, and the path will not leave the non-terminal symbol until the referenced diagram is left.

All terminal symbols, non-terminal symbols and syntax diagrams have exactly one flow line leading to them and exactly one flow line leading from them.

The graphic symbols used are shown in Figure 12/Z.100.


FIGURE 12/Z. 100

## Symbols in syntax diagrams

The SDL/PR syntax definition consists, on the "highest" level, of one syntax diagram, the SYSTEM. This diagram refers further, via non-terminals, to a set of other diagrams. Any path, starting with the flow line leading into this diagram and coming out of the diagram will on its path generate an $S D L / P R$ text. The text will be syntactically correct if the SDL syntax rules have been followed.

### 3.5 Common syntactic elements for $S D L / G R$ and $S D L / P R$

For certain syntactic elements, the same concrete syntax is used for both SDL/GR and SDL/PR.

### 3.6 Structure of the SDL Recommendations

Four Recommendations (Z.101 to Z.104) follow this Recommendation. The intention is to guide users to select a sub-set of SDL appropriate for their applications and methodology.

SDL may be applied in many fashions, supporting different purposes and methods. The minimum SDL sub-set which can be chosen is given in the Recommendation Z.101.


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FIGURE 13/Z. 100

## Structure of SDL Recommendations

Recommendations Z .102 to Z .104 contain extensions to the minimum sub-set of SDL, and should be applied when appropriate. The extensions may be applied in any combination.

Examples of the use of the concepts defined in the Recommendations are contained in Annexes. More comprehensive examples of the use of SDL are also contained in the SDL User Guidelines.

The contents of the following Recommendations may be briefly summarized:
Z. 101 Defines the basic concepts of SDL. The Recommendation forms the minimum sub-set of SDL to be applied. This sub-set of SDL is sufficient for describing the behaviour of systems.
Z. 102 Defines additional structural concepts, used to describe large and/or complex systems. They can be used both for describing the actual structure of a system and to describe the system on several levels of abstraction.
Z. 103 Defines the procedure concept, the composite operations, the macro concept, the option concept and the state orientated pictorial extensions (SDL/PE). These concepts are defined independently of each other, and may be applied in any combination.
Z. 104 Certain data concepts which are considered predefined in Z. 101 to Z. 103 are defined in Z.104. It should be noted that data may be used completely informally in SDL.
Z. 104 also contains a definition for the SDL abstract data type concept.

In addition to these Recommendations, a set of auxiliary documents is available, describing and explaining the language without having the status of being a Recommendation. Some of these documents are annexed to the Recommendations. The auxiliary documents are:

## The formal definition of SDL

This document contains the mathematical definition of the semantics of SDL. The definition is expressed in denotational semantics (VDM, META IV). It will shortly be available as a separate document. ${ }^{1)}$

## The SDL glossary

This document contains all SDL terms. Each term has a short explanation and reference to where it is defined in the Recommendations. The document is Annex A to the Recommendations, and appears in Fascicle VI. 11 of the Red Book.

## The SDL abstract syntax summary

This document contains a summary of the complete abstract syntax for the language. The abstract syntax is described in a short BNF-like form. The document is Annex B to the Recommendations, and appears in Fascicle VI. 11 of the Red Book.

## The SDL concrete syntax summary

This document contains a summary of all the concrete syntaxes of SDL; i.e. the Graphical Representation ( $S D L / G R$ ), the state orientated Pictorial Extension to the graphical form ( $S D L / P E$ ) and the textual Phrase Representation ( $S D L / P R$ ). The document is Annex C to the Recommendations, and appears in Fascicle VI. 11 of the Red Book.

## The SDL user guidelines

This document exemplifies and explains the use of SDL (without defining the language). It contains a number of examples and discussions on different usages of SDL. Some of the concepts defined in the Recommendations which should be used with special care are also discussed in the User Guidelines. The document is Annex D to the Recommendations and appears in Fascicle VI. 11 of the Red Book.

## The SDL course

This document is intended as training in the use of SDL. It is available as a separate document. ${ }^{2)}$
Finally, in the inside back cover of this fascicle, two templates are enclosed for use in drawing the graphical forms of SDL. They contain all the recommended graphical symbols, in their recommended format.

[^0]
## BASIC SDL

## Introduction

This Recommendation defines the basic CCITT Specification and Description Language (SDL). The basis for SDL is the concept of communicating finite state machines called processes. An SDL system is a set of blocks. Blocks are connected to each other and to the environment by channels. Within each block there are one or more processes. These processes communicate with one another by signals and are assumed to execute concurrently.

In defining the SDL, it was found useful to first define a common SDL model. This common model forms an abstract basis for the concrete syntaxes and ties them together. The concrete syntaxes are just alternate means of representing the concepts of SDL. Currently, there are two concrete syntaxes: SDL/GR and SDL/PR. Since these two syntaxes represent the same SDL concepts, it is possible to map a system defined using one form of SDL concrete syntax to the other concrete syntax.

In this Recommendation, the language is defined by first defining the common language model and then defining the SDL/GR and SDL/PR concrete syntaxes.

## 2 Common language model

### 2.1 An introduction to the common model

In SDL, a system is a set of blocks connected to each other, and to the environment of the system, by means of channels (see Figure 1/Z.101). The channels are unidirectional.


FIGURE 1/Z. 101

SDL Model

The behaviour of each block is modelled by one or more processes. A process is defined by a process definition.

Processes interact with other processes or the environment by means of signals. A signal is a flow of data conveying information between processes. When a process outputs a signal, the signal will be transported to the process it is directed to. The transportation mechanism for signals conveyed between processes in the same block is the same as for signals conveyed between processes in different blocks. Channels represent the transportation route for signals exchanged between blocks.

When a signal arrives at the process it is directed to, it will be retained outside the process until the process is ready to receive the input signal. A signal will be consumed when the destination process receives the signal.

SDL models open systems, this means that the system may interact with its environment. This interaction takes place solely by means of conveying signals via the channels leading to and from the environment. The environment is assumed to act in an SDL-like fashion, i.e., the environment can be considered to contain a process which outputs signals to the channels leading into the system and receives signals from the channels leading out of the system.

During its lifetime, a process is either in a state (waiting to receive one of a set of signals) or in a transition (performing a sequence of actions). When in a state only a specified set of signals can be received by a process. If one of these input signals is retained outside the process, it is received by the process. The receiving of the input makes the data carried by the signal accessible for the process and starts a transition. During a transition, the data of the process may be manipulated and signals may be output. The transition will end with the process entering a new state or with a stop.

A stop causes the process to cease to exist.
Common to the system and its environment is the concept of absolute time which is the same throughout the system and the environment.

Abstract syntax

## System definition

A system definition contains a system name, one or more block definitions, a set of channel definitions and a set of signal definitions.

A system definition contains the signal definition for each signal name contained in the signal list associated with each channel definition.

## Block definition

A block definition contains a block name, one or more process definitions and may contain signal definitions.

Each block definition contains the signal definition for each type of signal interchanged between processes within the block.

## Channel definition

A channel definition contains a channel name, an origin block definition identifier, a destination block definition identifier and a signal list. The signal list contains the identifier of each type of signal that may be conveyed through the channel.

The origin block definition identifier and the destination block definition identifier associated with a channel definition must be different and each must be the identifier of a block definition in the system definition or must be the environment.
The signal list associated with the channel definition contains at least one signal identifier.

## Signal definition

A signal definition contains a signal name and may contain a list of data type names.

## Process definition

A process definition contains a process name, a pair of integers and a process graph and may contain a formal parameter list, variable definitions and viewing definitions.

## Process graph

A process graph is a graph whose nodes are connected by directed arcs. An arc entering a node is called an incoming arc and an arc exiting the node is called an outgoing arc. A node having an arc as an incoming arc follows the node having the same arc as an outgoing arc.

The following categories of node exist:
State node
Input node
Task node
Output node
Decision node
Start node
Stop node
Create request node

The following rules define the connectivity of a process graph:

1) Each process graph contains one and only one start node. The start node is followed by a transition string. The start node does not follow any other node.
2) A transition string can be one of the following:
a) null followed by either a state node or a stop node;
b) an action string followed by a transition string;
c) a decision node.
3) An action string can be one of the following:
a) a task node,
b) an output node,
c) a create request node.
4) A decision node is followed by two or more decision arcs.
5) A decision arc is a named arc followed by a transition string.
6) A state node is followed by one or more input nodes.
7) An input node follows one and only one state node.
8) An input node is followed by a transition string.
9) The stop node has no nodes following it.
10) Each process graph has at most one stop node.
11) Each node is reachable from the start node.

## State node

A state node contains a state name and may contain a save-signal-set. State nodes within a process graph have different names.

## Input node

An input node contains a signal identifier and may contain an ordered set of variable identifiers.

## Save-signal-set

A save-signal-set contains signal identifiers.
Task node
A task node contains either a sequence of statements or informal text.

## Statement

A statement is either a set statement, a reset statement or an assignment statement.

## Set statement

A set statement contains a time expression and a timer identifier.

## Reset statement

A reset statement contains a timer identifier.
Assignment statement
An assignment statement contains a variable identifier, an assignment operator and an expression.

## Output node

An output node contains a signal identifier, a destination expression and may contain an actual parameter list.

## Decision node

A decision node contains a question and has at least two outgoing arcs. Each outgoing arc has associated with it a set of one or more answers to the question. Every possible answer to the question should be associated with one and only one arc. A question is either an expression or informal text. An answer is either a value identifier or informal text.

## Create request node

A create request node contains a process definition identifier and may contain an actual parameter list.

## Data type

Predefined data types exist for types: natural, integer, real, character, charstring, Boolean, time, duration, timer and process instance identifier. They are defined in Recommendation Z.104.

## Variable definition

A variable definition contains a variable name and a data type identifier and may contain a reveal attribute.

## Formal parameter list

A formal parameter list is an ordered set of formal parameters.

## Formal parameter

A formal parameter contains a formal parameter name and a type identifier.

## Actual parameter list

An actual parameter list is an ordered set of actual parameters.

## Actual parameter

An actual parameter is an expression.

## View definition

A view definition contains a variable identifier, a data type identifier and a process definition identifier.
The variable must have a reveal attribute in the process definition referred to by the process definition identifier. The revealing process definition referred to must belong to the same block as the viewing process definition.

## Expression

An expression is either a value identifier or a variable identifier or an operation.

## Operation

An operation contains either a viewing expression or an operator and a list of one more expressions.

## Viewing expression

A viewing expression is composed of a viewing operator plus a variable name and process instance identifier.

Interpretation rules

### 2.3.1 System

A system is a concrete entity, such as a telephone exchange, and is an instantiation of a system type defined by a system definition. A system is separated from its environment by a system boundary and contains a set of blocks. Communication between the system and its environment or between blocks within the system can only take place using signals. Within a system, these signals are conveyed on channels. The channels connect blocks to one another or to the system boundary.

The system possess a parameterless function of type time called NOW, yielding the current time. The current time is immediately available throughout the system and its environment. NOW can be used in expressions in any process in the system.

### 2.3.2 Channel

Within the system, there is a channel for each channel definition in the system definition. A channel is a transportation route for signals. The route is unidirectional. The end points of the channel are either a block or the system boundary. At least one of the end points of the channel must be at a block. If both end points are at blocks, the blocks must be different. The channel definition contains the list of all signals that may be conveyed on the channel.

When a signal is output to the channel, the signal is conveyed to the destination block. The order of the signals output to the channel and the order of the signals received from the channel is the same. If two or more signals arrive at a channel simultaneously, they are arbitrarily ordered.

### 2.3.3 Block

Within the system, there is a block for each block definition in the system definition. A block is an object of manageable size in which one or more processes can be interpreted. There are 2 communication mechanisms between processes within the same block: signals and shared values.

When a signal arrives at the block from a channel, the block delivers the signal to the input port of the process addressed by the process identifier in the signal.

When a signal is output by a process within the block, it is delivered to the process addressed by the process identifier in the signal. If the addressed process is within the same block, the block delivers the signal to its input port. If the addressed process is in another block, the block delivers the signal to the channel able to convey that signal.

Shared values allow a process to view a revealed variable in another process. Only the revealing process is allowed to change the value of the variable. The viewing process receives the current value of the revealed variable by using a viewing operator.

### 2.3.4 Signal

A signal is a flow of data conveying information between processes and is an instantiation of a signal type defined by a signal definition. A signal can be sent by either the system environment or a process and is always directed to either a process or the environment.

Each signal contains the signal identifier in the signal definition, an origin process instance identifier and a destination process instance identifier. In addition, other values may be conveyed by variables in a signal. In a signal, there is one variable for each name in the data type list in the signal definition.

### 2.3.5 Process

A process is a communicating finite state machine and is an instantiation of a process type defined by a process definition. Within a block there may be zero or more processes for each process definition. Processes can exist from the time that a system is created or can be created by create request actions and may cease to exist by performing stop actions. A process executes independently from and concurrently with other processes in the system.

All processes in the system possess four predefined variables of process identifier type called: SELF, PARENT, OFFSPRING and SENDER. These variables are process instance identifiers for:

- the process (SELF);
- the creating process (PARENT);
- the most recently created process (OFFSPRING);
- the process from which the last input signal has been received (SENDER).

These variables can be used in expressions but cannot explicitly be assigned a value. For all processes present at system initialization, PARENT is given the same distinct value, which is different from the value of SELF for any process.

Signals to the process are input signals and signals from the process are output signals. An input signal is an entity intended to invoke the process and to communicate information to it. An output signal is intended to invoke another process and to communicate information to it.

The set of signal identifiers that appear attached to input nodes of the process graph denotes the set of valid input signal identifiers for this process definition. For each state, all input signal identifiers appear in either a save-signal-set or an input node.

The pair of integers contained in the process definition define the number of instances of the process which are created when the system is created and the maximum number of simultaneous instances of the same process type. When a system is created, the initial processes are created in a random order and no actual parameters are passed to the process.

When the process is created, it is given an empty input port, and variables are created with undefined values. Then the process starts by interpreting the start node in the process graph.

When a valid input signal arrives at the process, it is put into the input port of the process. Each process contains a single input port. The input port may retain any number of input signals so that several input signals are queued for the process. The set of retained signals are ordered in the queue according to their arrival time. If two or more signals arrive simultaneously, they are arbitrarily ordered. Attached to the input port is a possibly empty set of timers. Each timer contains a value of the time type.

The process is either waiting in a state or active performing a transition. For each state, there is a save-signal-set. When waiting in a state, the first input signal whose identifier is not in the save-signal-set is taken from the queue and received by the process. The input port will continuously compare NOW with the timer, if any exists, having the lowest value greater than zero. When the value of NOW is greater than or equal to the value of this timer, a signal with the same name as this timer is placed in the queue and then the timer is given the value of zero.

When a process is waiting, it is always in a unique state denoted by the corresponding state node in the process graph. When an input signal is received, the process becomes active, interprets the input node having the same name as the input signal and performs a transition leading to a new state.

### 2.3.6 Process graph

A start node is interpreted as a start action. The start action causes the node following the start node to be interpreted.

An input node is interpreted as an input action which receives and consumes the given signal and then the node following the input node is interpreted. The consumption of the signal makes the information conveyed by the signal available to the process. The variables in the input node are assigned the values of the corresponding variables in the signal. If there is no variable in the input node for a variable in the signal, the value of the variable is discarded. SENDER in the receiving process is given the value of the origin process instance identifier carried by the signal.

A task node is interpreted as a task action. The task action is the interpretation of a sequence of statements or informal text. When the action is complete, the node following the task node is interpreted

A set statement will cause a reset statement on the timer given in the statement and will assign the given time value to the timer.

A reset statement will set the time value of the timer to zero. If any signals having the same name as the timer are present in the input queue, they will be removed from the input queue and will be discarded. All signals in the queue with the same identifier as the timer signal identifier are removed from the queue and discarded.

An assignment statement is informally interpreted as the value of the variable in the assignment statement takes on the value of the expression in the assignment statement.

An output node is interpreted as an output action which creates a signal and delivers it to the block. Then the node following the output node is interpreted. The output signal is an instantiation of a signal type defined by the signal definition indicated by the signal identifier in the output node. The variables in the signal are assigned the values of the actual parameters in the output node. If there is no actual parameter in the output node for a variable in the signal, the variable has undefined value. The origin process instance identifier carried by the signal is assigned the value of the SELF variable. The destination process instance identifier of the signal is assigned the value of the destination expression contained in the output node.

A decision node is interpreted as a decision action which answers a question. The arc which matches the answer to the question is chosen and the node following this arc is interpreted.

A state node is interpreted as the termination of a transition by giving the process a new state as denoted by the name contained in the node. The input port is informed that the process is now waiting in a state and is also presented the save-signal-set attached to the interpreted state node. After this, the process waits until given a new input signal.

A stop node is interpreted as the immediate termination of the process. This means that the input signals retained in the input port are discarded and that the variables created for the process, the input port and the process will cease to exist.

A create request node is interpreted as a create request action. The create request action causes the creation of a process in the same block. The definition of the process is in the same block and is identified by the process identifier in the create request node. As part of the create request action, the created process's PARENT variable is given the value of the creating process's SELF variable. The created process's SELF variable and the creating process's OFFSPRING variable are both assigned the same unique process instance identifier value. The formal parameters in the newly created process are assigned the values of the actual parameters contained in the create request node.

### 2.3.7 Data type

The predefined data types are used in the normal sense

### 2.3.8 Variable

A variable can be assigned a value. The contents of the value assigned to a variable can be later retrieved from the variable. A variable also has a data type which restricts the class of values which can be assigned to the variable.

Within a process, there is a variable for each variable definition in the process definition. The value of a variable can only be modified by the process that defines the variable. The value of a variable is known only to the process that defines the variable unless the variable has the reveal attribute. The reveal attribute allows other processes in the block to view a variable. Variables possess the same lifetime as the declaring process (i.e. they are created when the declaring process is created and they cease to exist when the declaring process ceases to exist).

Within a signal, there is an anonymous variable for each occurrence of each data type name in the signal definition. The value of the variable can only be assigned in the output node that created the signal and can only be known in the input node that receives and consumes the signal. These variables have a lifetime bounded by the lifetime of the signal.

### 2.3.9 Expression

An expression is informally interpreted as producing a value.

### 2.3.10 View definition

A view definition defines a variable name which may only be used in a viewing expression to obtain the value of a variable owned by another process.

### 2.3.11 Viewing expression

The value of a viewing expression is the value of the variable identified by the variable name and process instance identifier in the viewing expression.

## 3 <br> SDL/GR

A system definition is represented in SDL/GR syntax by:

- a block interaction diagram which contains the system name and the channel definitions and which identifies the block definitions. The block interaction diagram also identifies the process definitions which model each block's behaviour. The block interaction diagram may denote: 1) the lists of signals that pass between processes in the same block; 2) the lists of signals conveyed by channels between blocks, and 3) the creation of new process instances by other process instances;
- process diagrams which define the behaviour of each process and are the graphic representations of the process definitions. Process diagrams may contain variable definitions, formal parameters and view definitions;
- signal lists which name the signals conveyed by a channel or from one process to another inside the block. These may be incorporated in the block interaction diagram, using signal list symbols, or presented as separate lists in whatever form is felt suitable;
- signal definitions which give the data types and order of the data values which can be contained in a signal, for each signal named in the signal lists. These are specified using SDL/PR syntax.

In a system definition, names and identifiers may be used. Names are specified using SDL/PR syntax. Identifiers consist of a name together with qualifiers. A qualifier is the entity type with which the name is associated, and it represents the hierarchy level of the entity which is being identified. No two or more entities may have the same identifier. In SDL/GR, the qualifiers of names may be inferred from the context, but whenever they are used, they are specified using SDL/PR syntax.

### 3.1 Block interaction diagrams

The block interaction diagram for a system contains a system name, a set of block symbols, environment symbols, and a set of channel symbols and signal list symbols.

### 3.1.1 Symbols

The recommended symbols appear in Figure 2/Z. 101 below.


FIGURE 2/Z. 101

Block interaction diagram symbols

- The environment symbol represents the system environment and may appear a number of times.
- A block symbol contains a name, a nonempty set of process symbols, signal route symbols and may contain create symbols and signal list symbols.
- A process symbol contains a process name and may contain a formal parameter list symbol. The process name is the same as the name contained in the process definition which describes the behaviour of the process. The formal parameter list symbol contains a list of the names of the formal parameters which are initialized either when the system is created or when the process instance is dynamically created.
- A pair of integer values may be associated with a process symbol, the first value represents the number of instances of the process which exist when the system is created, the second value represents the maximum number of simultaneous instances of this process type. The two values are positioned in the top right-hand corner of the process symbol.

The default for the first value is one. The default for the second value is infinity. This pair of integers is specified using the SDL/PR syntax. When one of the integers is not specified, the default value is chosen for it.

- A channel symbol has a channel name attached to it. The channel symbol has an origin end which is connected to a block symbol and a destination end which is connected to another block symbol. Alternatively, either the origin or the destination connection (but not both) may be connected to an environment symbol instead of a block symbol. A signal list symbol may be placed beside a channel symbol to identify the signals carried by the channel.
- A signal route symbol in a block is associated with a signal list symbol. A signal route symbol leads either from one process to another, or from a process to the origin end of a channel (at the block boundary), or from the destination end of a channel (at the block boundary) to a process.
- A signal list in a block interaction diagram is a list of names, the whole enclosed in the signal list symbol (i.e., in square brackets). The signal list may itself have a name, which is written above the symbol. Entries in the list (which are separated by commas and can be put in columns or rows) are the names of individual signal definitions and the names of other signal lists. Within the list, signal list names are distinguished from individual signal definition names by enclosing each signal list name in a further pair of square brackets. If it is decided to include signal lists on the block interaction diagram using signal list symbols, all signal lists should be included in the diagram. Figure 3/Z.101 shows examples of signal lists.


FIGURE 3/Z. 101

## Examples of signal lists in block interaction diagrams

- Create symbols lead from one process symbol to another process symbol. The former process symbol represents the "creating" process. The latter process symbol represents the "created" process.


### 3.1.3 Drawing rules

- Channel symbols are connected to the boundaries of block symbols with which they are associated. Channel symbols should join block symbol boundaries at $90^{\circ}$. If necessary, channel symbols may contain $90^{\circ}$ bends. A channel symbol includes an arrowhead to show the direction of the flow of signals along the channel.
- Signal route symbols are connected to the boundaries of block symbols or process symbols with which they are associated. Signal route symbols join these boundaries preferably at $90^{\circ}$. If necessary, signal route symbols may contain $90^{\circ}$ bends. Several signal route symbols may converge at the origin end of a channel (at the block boundary). Several signal route symbols may diverge from the destination end of a channel at the block boundary. A signal route symbol includes an arrowhead at one end to show the direction of the flow of signals.
- Create symbols are connected to process symbol boundaries by dotted lines which meet the process symbol boundaries at $90^{\circ}$. Arrowheads are used on these connecting lines so that the "creating" process symbol points to the "created" process symbol.
- The preferred orientation of symbols is shown in Figure 2/Z.101.
- The size of symbols may be chosen by the user.
- Symbol boundaries must not overlay or cross. An exception to this rule applies for the channel symbols and signal route symbols which may cross each other. There is no logical relationship between channel symbols or signal route symbols which do cross.


### 3.2 Signal lists

The union of all signal names in the signal lists associated with signal route symbols connected to a given process definition equals the set of valid input signal names for that process.

The union of all signal names in the signal lists associated with signal route symbols connected to the origin end of a channel equals the list of names in the signal route list associated with that channel, and equals the union of all signal names in the signal route lists associated with signal symbols (in the channel destination block) connected to the destination end of that channel.

### 3.3 Process diagrams

### 3.3.1 Symbols

The behaviour of a process is represented in graphical form by a process diagram. The name of the process diagram is the same as the process name in the process definition which it represents. Figure $4 / \mathrm{Z} .101$ shows the symbols that are used in the process diagrams of SDL/GR form.

### 3.3.2 Relationship between $S D L / G R$ process diagrams and the SDL abstract syntax and the use of symbols

Each process diagram symbol listed in Figure 4/Z.101 represents the equivalently named node of the process graph in the abstract syntax. Flow lines, which connect symbols, represent the directed arcs which connect nodes. Allowable connections of symbols by flow lines in an SDL-GR process diagram are shown in Figure 5/Z.101.

The formal parameters, valid input signal set, variable definitions, view definitions, expressions and viewing expressions are specified using SDL/PR syntax.

A start symbol represents a start node (see also § 2.2.3.3). The start symbol contains the name of the process it describes.

A stop symbol represents the stop node.


FIGURE 4/Z.101

SDL/GR process diagram symbols


FIGURE 5/Z. 101
Allowable connections of symbols by flowlines in an SDL/GR process diagram

A state symbol represents one or more state nodes and contains one or more state names separated by commas, or an asterisk, or an asterisk followed by a list of state names within brackets.

A save symbol represents the set of saved signals attached to a state node. It contains one or more signal names, separated by commas, or an asterisk.

An input symbol represents one or more input nodes. Signal names which are contained in the input symbol are separated by commas. Each of these signal names gives the name of one of the input nodes which this input symbol represents.

A task symbol represents a task node. The task symbol contains task name and may contain either a sequence of statements or informal text.

A create request symbol represents a create request node. It contains a create request action as specified in SDL/PR syntax.

A decision symbol represents a decision node. It contains a question and may contain a decision name. Two or more flow lines lead from the decision symbol to other symbols; each such flow line has attached to it (i.e., written alongside or inserted in a break in the flow line) its own answer name. The ELSE answer implies an answer which is for any answer that is not covered by any other answer name.

An output symbol represents one or more output nodes. Signal names which are contained in the output symbol are separated by commas. Each of these signal names gives the name of an output node which this output symbol represents. The destination process instance identifier can optionally be given in the output symbol using the SDL/PR syntax (that is, a TO keyword followed by an expression of the type process instance identifier, the TO keyword is after the list of signal names). Where the destination process of a signal cannot be uniquely determined because neither the signal name nor the context is sufficient to allow this, the process instance identifier is required.

A nextstate symbol represents an arc connecting the last node in a transition string to the following state node.

A flow line connecting two other symbols (representing nodes) represents the arc connecting the corresponding nodes.

A comment symbol is used to attach informal text to any other symbol.
An in-connector contains a label and represents the continuation of a flow line from a corresponding out-connector which contains the same label.

### 3.3.3 Graphical conventions

### 3.3.3.1 Implicit transitions

The abstract syntax of SDL requires that either a save or an input leading to a transition be specified for every signal in the valid input signal set of a process for every state of the process. SDL/GR provides implicit "null" transitions for any signals for which neither transitions nor saves are given explicitly. A null transition is equivalent to a connection from a state symbol to an input symbol which is then connected back to the same state symbol. For a given state, SDL/GR thus discards any signals which are not explicitly mentioned in conjunction with that state. Also the data contained by such signals is discarded.

If no start symbol appears in an SDL/GR process diagram, an implicit start symbol which is directly connected to the "starting" state symbol is assumed. The starting state may be identified by implication from its name, or by a comment.

### 3.3.3.2 Flow lines and connectors

Where two or more symbols are followed by a single symbol, the flow lines leading to that symbol converge. This convergence may appear as one flow line flowing into another or as more than one out-connector associated with a single in-connector, or as separate flow lines entering the same symbol.

Where a symbol is followed by two or more other symbols, a flow line leading from that symbol may diverge into two or more flow lines.

Arrowheads are required whenever two flow lines converge and whenever a flow line enters an outconnector or a state symbol. Arrowheads are prohibited on flow lines entering input symbols. In all other circumstances, the arrowheads are optional.

### 3.3.3.3 Multiple appearance

Whenever state symbols, or connector symbols, appear having the same name, they are considered to represent the same semantic entity. The resulting entity is considered to have the union of all incoming and outcoming flow lines from all its multiple representations. Whenever one or more stop symbols appear on the same process diagram, they all represent the stop node.

### 3.3.3.4 Shorthand notation

A shorthand notation is provided to allow reference to all, or all other signals, or states, in either the input, save or state symbol.

An input symbol attached to a state and containing an "*" (asterisk) indicates that the following transition applies to all incoming signals that do not appear otherwise in input symbols or save symbols attached to any appearance of that state symbol. Only one input symbol or one save symbol containing an "*" is allowed for any state.

A save symbol attached to a state and containing an "*" indicates that all signals that do not appear in input symbols attached to any appearance of that state symbol should be saved.

An "*" in a state symbol denotes all states in that process and indicates that the following transitions or saves should be interpreted in every state. An "*" followed by a list of state names in brackets indicates that the following transitions or saves should be interpreted in every state except for those listed. Such state symbols must not have any incoming flow lines.

An "-" in a nextstate symbol means that the following state is the same state from which the current transition was started. The " -" is not allowed in a nextstate symbol that follows the start symbol.

A nextstate symbol and a state symbol can be merged only if they represent the same state symbol.

### 3.3.3.5 Miscellaneous

All symbols of the same type shall preferably be of the same size within any one diagram.
The preferred orientation of symbols is horizontal and the preferred aspect ratio of symbols is $2: 1$.
Mirror images of input and output symbols are allowed.
Flow lines are horizontal or vertical and have sharp corners.
Flow lines that cross do not have a logical relationship.
The text associated with a symbol should be placed within that symbol where practical.

### 3.3.3.6 SDL template

A template suitable for hand drawing the basic set of SDL symbols is enclosed with the SDL user guidelines.

### 3.4 Text extension symbol

A text extension symbol may be attached to all SDL/GR symbols. The text contained in this symbol is to be regarded as contained in the symbol to which the text extension symbol is attached. The text extension symbol is shown in Figure 6/Z.101.


FIGURE 6/Z. 101

In all SDL/GR diagrams, comments may be inserted wherever the user finds it appropriate. The comments may be inserted by using either the SDL/GR comment symbol (see Figure 7/Z.101) or the SDL/PR syntax for comments (see § 4.3.2, lexical rule 7).

$$
---\{<\text { comment text }>
$$

FIGURE 7/Z. 101

## Comment symbol



FIGURE 8/Z. 101

## Examples of comments in SDL/GR

## 4 <br> Linear syntax

### 4.1 General

This section defines SDL/PR and relates it to the common language model (see § 2).
A system definition in the SDL/PR syntax is represented by a sequence of statements bounded by the words SYSTEM and ENDSYSTEM.

The detailed rules for the SDL/PR syntax are contained in the syntax diagrams (see § 4.3)
Reference to a named entity outside its definition is made by an identifier. The identifier is composed of a name and an optional qualifying part. The qualifying part must be used when the name alone will not uniquely determine the item being referred to.

### 4.2 Keywords

SDL/PR uses a number of keywords to express SDL concepts as defined in the abstract syntax. Some of the keywords are used in pairs to reflect the structuring of SDL into SDL/PR.

The word "embrace" is used with these word pairs to indicate their role as delimiters.

| SYSTEM | embrace the concept of system definition (the SDL/PR representation of a system |
| :--- | :--- |
| ENDSYSTEM | starts with the keyword SYSTEM and ends with the keyword ENDSYSTEM). |
| BLOCK | embrace the concept of a block definition. |
| ENDBLOCK |  |
| PROCESS | embrace the concept of a process definition. |

### 4.2.2 $\quad$ Single keywords concerned with definitions

The keywords in this paragraph are used to indicate that a definition follows.
DCL introduces the representation of the variable definition. The keyword REVEALED is used within a DCL statement to identify revealed variables.

VIEWED introduces the representation of the view definition.
SIGNAL introduces the representation of the signal definition.
CHANNEL introduces the representation of the channel definition. The keyword FROM is used within the CHANNEL definition to indicate the origin block of the channel and the keyword TO is used to indicate the destination block. The keyword ENV is used to refer to the environment. The keyword WITH is followed by the list of the signals carried by the channels.

FPAR introduces the representation of the formal parameter definition.
DURATION
TIME
TIMER
NATURAL
INTEGER
REAL
CHARSTRING
CHARACTER
BOOLEAN
PID
represent the predefined data types.

VIEW introduces the representation of the viewing expression. It is used within an expression wherever a variable declared as VIEWED is used.

SET introduces the representation of the set statement.
RESET introduces the representation of the reset statement.
SYSTEM
BLOCK
PROCESS
4.2.3 Keywords associated with nodes in a process graph

The process graph in the abstract syntax consists of nodes connected by directed arcs.
Keywords are chosen to correspond to nodes, and the arcs which connect nodes in the abstract syntax are represented by the ordering in which the keywords occur (see § 4.2.5).

START represents the start node. If this keyword is not present, the first STATE keyword, following PROCESS, represents the starting state.

STATE introduces the representation of one or more state nodes. The save-signal-set attached to a state node is represented by the keyword SAVE followed by one or more signal identifier:.

INPUT introduces the representation of one or more input nodes.
TASK introduces the representation of a task node.
OUTPUT introduces the representation of one or more output nodes. The destination process instance identifier can optionally be given by the keyword TO followed by an expression which yields a process instance identifier value. Where the signal destination cannot be uniquely determined, the keyword TO is required.

## DECISION ENDDECISION

embrace the concepts of a decision node. The keyword ELSE is used to represent the answer for all cases not explicitly named.

CREATE
STOP introduces the representation of a create request node. represents a stop node.
4.2.4 Keywords associated with arcs

JOIN represents an arc between nodes that are not state nodes. The first node is generally represented by the keyword immediately before the keyword JOIN, the second node is always identified by having the same label identifier as the keyword JOIN. There are some exceptions to this general explanation as far as the first node is concerned (see § 4.2.5).

If the second node is another JOIN, the arc is connected with the node that this JOIN refers to.

If the keyword having the join label is NEXTSTATE, the second node is the state with the same name (the NEXTSTATE rules are valid).

NEXTSTATE represents an arc. The first node of the arc is represented by the keyword immediately before the keyword NEXTSTATE, the second node is the state with the same name.

### 4.2.5 Representation of arcs in $S D L / P R$

The representation rule of an arc in SDL/PR is given by the keywords ordering.
There are some exceptions to this general meaning in case of keywords such as JOIN and NEXTSTATE as it is said in the previous paragraph.

Moreover, when a keyword (associated with a node or an arc) immediately follows an answer, the first node of the arc is the preceding matching decision.

If the keyword immediately before a keyword associated with a node or an arc is ENDDECISION, the first nodes of the arcs are represented by the last keywords in all transition strings of the decision having no terminator statements.

The last keyword of a decision branch represents a node not connected with the keyword that follows the next result name, but connected with the keyword after the ENDDECISION. This rule is clearly not valid if the last keyword of a decision branch is a terminator statement.

### 4.3 Reserved words in SDL/PR

Certain words are reserved in SDL/PR and may not be used as names. The list of reserved words is found in Annex C. 2 to Recommendations Z. 100 to Z.104.

## SYSTEM DEFINITION



BLOCK DEFINITION


CHANNEL DEFINITION


SIGNAL LIST


## SIGNAL DEFINITION



## PROCESS DEFINITION



## VALID INPUT SIGNAL SET



TYPE LIST


PROCESS BODY


STATE BODY


STATE LIST


INPUT LIST


## SAVE LIST



VARIABLE DEFINITION


VIEW DEFINITION


NUMBER OF INSTANCES


FORMAL PARAMETERS


## TRANSITION STRING



## ACTION STATEMENT



TASK


## STATEMENT



INFORMAL TEXT


## TERMINATOR STATEMENT



TERMINATOR


## OUTPUT



END


## CREATE REQUEST



ACTUAL PARAMETERS


## ASSIGNMENT STATEMENT



RESET STATEMENT



DECISION


QUESTION


## ANSWER



## VIEWING OPERATOR



LABEL


COMMENT


## IDENT


4.4.1 Lexical units

### 4.4.1.1 Lexical rules

- All the punctuation marks [e.g., . ; $\left.{ }^{\prime}:!=()\right]$ and operation symbols (e.g. $+,-,{ }^{*},<,>\ldots$ ) are lexical units which may take the place of spaces.
- Two lexical units must be separated by one or more spaces.
- Keywords belong to the same lexical category as namestring, and they are reserved.
- Outside lexical units several spaces have the same "meaning" as one space.
- Tabulation characters (VT, HT, CR, BS . . .) may be considered as spaces.
- All letters and nationals are always interpreted as if uppercase, except with a charstring.
- Wherever spaces may occur comments may be inserted delimited by '/*' and '*/', these comments have the same meaning as one space. The comment must not contain the special sequence ' $* /$ '.

LABEL STRING


NAME STRING


## QUALIFIER



STRUCTURAL NAME


ENTITY TYPE NAME


DECIMAL INTEGER


## DECIMAL DIGIT



## LETTER

## 

SPECIAL


NATIONAL


The above referenced positions
refer to the positions in the CCITT
International Alphobet No. 5
reserved for notional use

## PREDEFINED DATA TYPE NAMES



## Recommendation Z. 102

## STRUCTURAL CONCEPTS IN SDL

## Introduction

This Recommendation defines a number of concepts needed to handle hierarchical structures in SDL. The basis for these concepts is the SDL as defined in Recommendation Z. 101 and the defined concepts are strict additions to those defined in Recommendation Z.101. There is no conflict between the definitions contained in this Recommendation and those contained in Recommendations Z. 103 and Z. 104.

The intention with the concepts introduced in this Recommendation is to provide the user of SDL with means to describe large and/or complex systems. The SDL as defined in Z.101 is suitable for specifying or describing relatively small systems which may be understood and handled at a single level of blocks. When a larger, or complex system should be represented there is a need to partition the system specification or description into manageable units, which may be handled and understood independently. It is often suitable to perform the partition in a number of steps, resulting in a hierarchical structure of units representing the system.

There is also a need to use structural concepts in order to specify or describe the required or actual structure of a system.

This Recommendation defines concepts for the partitioning of:
blocks into sub-blocks, sub-channels and new channels, channels into blocks and channels,
processes into sub-processes.
The concepts are such that the resulting hierarchical structure, representing the system, will provide the reader with series of overviews from which he can gain a general appreciation before descending to a more detailed description. This means also that the concepts will support design technologies aiming at "stepwise refinement" by adding more detailed information in a number of steps.

## 2

## Common language model

### 2.1 General

In Recommendation Z .101 a system is described as composed of a set of blocks connected to each other and to the system boundary by unidirectional channels. This Recommendation introduces concepts for describing the partitioning of blocks, channels and processes into sub-components.

Each block, in a system, may be partitioned into one or more sub-blocks. In this partitioning, new channels are introduced to connect the sub-blocks to each other; in addition, the channels terminating at and originating from the partitioned block may be split into sub-channels.

Block A is partitioned into:


FIGURE 1/Z. 102

## The partitioning of a block

A sub-block, in turn is a block and may be partitioned. This partitioning may be repeated any number of times resulting in a hierarchical structure of blocks and their sub-blocks. The sub-blocks of a block are said to exist on the next lower level in the block tree:


FIGURE 2/Z. 102
A Block-tree

When a block is partitioned into sub-blocks, the rule from Recommendation Z. 101 that a block definition should contain one or more process definitions is relaxed, and is only valid for a block which is not further partitioned (i.e. the "leaf"-blocks in the block tree describing the system must contain processes). However, if a block definition contains process definitions, the sub-block definitions must include at least the sub-process definitions resulting from the partitioning of the processes.

The sub-channels resulting from the block partitioning are channels.
Channels may also be partitioned. This results in a set of new blocks, new channels, one incoming channel, and one outgoing channel:

C [1, $]$
CHANNEL C is partitioned into:

cciti-73780

FIGURE 3/Z. 102

The partitioning of a channel

Note that the signal list associated with the original channel C is associated with the incoming and outgoing channels.

Both the partitioning of blocks and the partitioning of channels leaves unchanged the interfaces of the partitioned objects.

A process definition may be partitioned into a set of sub-process definitions. These two descriptions of the behaviour are alternative in the sense that when the system definition is interpreted either the set of sub-process definitions or the process definition is interpreted. The process definition is to be considered as an alternative description with relation to the set of sub-process definitions.

A sub-process is a process, and may in turn be partitioned into sub-processes. The resulting hierarchy of processes is represented in a process tree.


CCTIT-73790

FIGURE 4/Z. 102
Process - sub-process relation

As sub-processes are processes, the behaviour described by the partitioned process is partitioned into a set of concurrent "sub-behaviours". Methods to ensure that this partitioning is correct are necessary but not part of the SDL.

The partitioning of a block into sub-blocks, and its processes into sub-processes may be done at the same time. As a process has to be contained in a block, its sub-processes have to be contained in sub-blocks of the block containing the partitioned process. The partitioned blocks and processes may be regarded as separate structures related to each other:


FIGURE 5/Z. 102
Relation between block and process trees

If a block is partitioned, then any process it contains may also be partitioned, in which case all its sub-processes must appear in the sub-blocks of the block. If the process is not partitioned, then it must appear in one of the sub-blocks. In order to further describe the behaviour of the sub-blocks new processes and signals may also be included in the sub-blocks irrespective of whether there were processes in the block. However, the "leaf"-blocks must contain processes.

If, in the total partitioning representation of a system; process definitions appear on more than one level, then several consistent sub-sets of the representation may be found. A consistent sub-set is a selection of the block definitions and process definitions in the total representation such that:
a) It contains the highest level in the block tree;
b) If it contains a block it must contain its parent;
c) If it contains a sub-block of a block, it must also contain all other sub-blocks of that block;
d) All "leaf"-blocks in the resulting structure contain processes.


FIGURE 6/Z. 102

## A consistent sub-set of a system representation

If processes appear in a system definition at more than one level, then several consistent sub-sets of the representations may be found. These sub-sets represent alternative descriptions of the system, with various degrees of detail. They may be used to provide readers with both overviews and detailed descriptions. They may be chosen so they support the interpretation of the system on alternative levels of abstraction. If several alternative representations of the behaviour exist, all but the most detailed one are to be considered as overviews of the behaviour.

This abstract syntax is based on the abstract syntax given in Recommendation Z.101. Only the additions to the definitions in Recommendation Z. 101 are given here.

## Block definition

A block definition may also contain an internal part block definition, and if it does so it need not contain process definitions.

## Internal part block definitions

The internal part block definition contains one block substructure definition and it contains one process substructure definition for each of the process definitions contained in the block definition. It may also contain signal definitions and data type definitions.

## Block substructure definition

A block substructure definition may contain one or more sub-block definitions and one or more channel definitions.
For each of the terminating endpoints of sub-channels of the enclosing block there must be at least one sub-channel definition having that endpoint as originating endpoint, and the reverse must hold for all originating sub-channel endpoints of the enclosing block. The union of the signal lists of the sub-channel definitions having the same endpoint as a subchannel leading to or from the enclosing block must be identical to the signal list of that block, in addition to this signal lists of the sub-channel definitions originating from a terminating endpoint must be disjoint.

All channel definitions contained in the block substructure definition must either connect sub-blocks to channel endpoints of the enclosing block or sub-blocks to each other.

## Sub-block definition

A sub-block definition is a block definition.

## Channel definition

A channel definition may also contain a channel substructure definition.

## Sub-channel definition

A sub-channel definition is a channel definition.

## Channel substructure definition

A channel substructure definition contains two or more channel definitions, one or more block definitions, and may contain signal definitions.

All channel definitions contained in the block substructure definition must connect sub-blocks to each other, and all sub-channel definitions must connect channel endpoint of the enclosing block to sub-blocks.

## Process substructure definition

A process substructure definition is associated with a process name and contains one or more process names, each associated with a sub-block name.

The associated sub-process name must be the name of a process definition contained in the enclosing block definition. The contained process names must be names of sub-process definitions contained in the block definition having the associated sub-block name.
Each signal name in the valid input signal set of the associated process must appear in exactly one of the valid input signal sets of the sub-process definitions having the contained sub-process names. Each signal name attached to the output node of the associated process must be attached to at least one output node of the sub-process definitions having the contained sub-process names.

## Sub-process definition

A sub-process definition is a process definition.

### 2.3 Interpretation

The interpretation rules given below are defined as additions to the corresponding set of rules defined in Recommendation Z.101.

If a channel definition contains a channel substructure definition then either the channel may be interpreted, as defined in Recommendation Z. 101 or the channel substructure definition may be interpreted.

If the channel substructure definition is interpreted, every signal delivered to the originating endpoint of the channel is given to the channel substructure, and every signal delivered by the channel substructure is given to the terminating endpoint of the channel.

## Channel substructure

A signal delivered to the channel substructure is given to the incoming channel and a signal delivered by the terminating endpoint of the outgoing channel is delivered to the enclosing channel.

## Block

If a block definition contains one or more process definitions and also contains an internal part block definition then either the block may be interpreted as defined in Recommendation Z.101, or the internal part block may be interpreted. If the block contains no process definitions, the internal part block must be interpreted.

If the internal part block is interpreted, all signals delivered to the block will be given to the internal part block, and all signals delivered by the internal part block will be further delivered to channels leading from the block in the same manner as if delivered from a process contained in the block.

## Internal part block

Each process in the enclosing block is replaced by a process substructure.
If a signal given to the internal part block from the enclosing block is addressed to a process, then the signal is given to the process substructure, else it is given to the block substructure.

A signal, delivered by the block substructure will be given to the enclosing block. If that signal was sent from a process appearing as a sub-process of a process substructure, the sender-attribute of the signal will be modified to the process instance identifier of the replaced process.

## Block substructure

A block substructure contains blocks and channels, according to the block substructure definition, these are interpreted according to the rules defined for blocks and channels.

## Process substructure

A process substructure instance replaces one process instance of the referenced process definition. It also denotes a set of sub-process instances, one instance for each sub-process name in the definition. Each sub-process is allocated to the block with the associated block name.
Each signal given to the process substructure will be re-addressed to the sub-process which has the signal name in the valid input signal set and given to the block substructure of the enclosing block.

## 3 Graphic syntax

The following graphic syntax is an addition to the syntax defined in Recommendation Z.101. The additions cover the representation of the structure and partitioning of a system.

An overview of the structure of a system is given by the Block Tree Diagram. The partitioning of blocks, processes and channels into sub-components is represented in the Block Interaction Diagram and the Channel Substructure Diagram.

The set of documents and diagrams describing the system may be large. It is essential that the documents are related to each other by references and proper titles, however syntactic means for doing this do not form part of the SDL graphic syntax.

### 3.1 Block tree diagram

The block tree diagram is intended to give an overview of the structure of a system, i.e. the partitioning of the system into a hierarchical structure of blocks. Details on how the blocks are connected by channels are given in the block interaction diagram.

A part of the diagram may also be used to give an overview of how a block is partitioned into sub-blocks. In this case, the partitioned block is shown as the root box.

The symbol used in a block tree diagram is a box which represents a system or a block. The name of the represented object should appear inside the box.

Each block (box) is connected downwards to its sub-blocks (boxes) to form a hierarchical tree, as the example given in Figure 7/Z. 102 below:


FIGURE 7/Z. 102

## Example of a block tree diagram

### 3.1.2 Relationship to the SDL abstract syntax

The structure shown has its equivalence in the system definitions, and in the block substructure definitions of the blocks in the system.

### 3.1.3 Graphical conventions

The tree should preferably be drafted so that the blocks at the same level appear beside each other in the representation.

As a block tree diagram of a large system will also be large, it may be suitable to split the diagram into several diagrams. This splitting should be such that the first diagram, having the system as the root, is chopped off so that a set of further partitioned blocks appears as not partitioned. In the following diagrams these blocks appear as roots. For example, in Figure $8 /$ Z. 102 the diagram from Figure $7 /$ Z.102 is split in two diagrams.


FIGURE 8/Z. 102

Example of splitting a block tree diagram into several diagrams

This diagram represents the partitioning of a block into sub-blocks, sub-channels and (new) channels. The diagram has basically the same form as the block interaction diagram, introduced in Recommendation Z.101, representing the partitioning of a system into blocks and channels.

### 3.2.1 Symbols

The symbols used to represent a block interaction diagram are shown in Figure 9/Z.102 below:


FIGURE 9/Z. 102

Symbols used in a block interaction diagram

In addition to these symbols, signal definitions may appear in the diagram, using the SDL/PR syntax.
The rules for connecting the symbols are the same as for the block interaction diagram (see Recommendation Z.101), with the only exception that in the title of the diagram, it should be made clear that the diagram is a block interaction diagram for a block. A simple example of a block interaction diagram is given in Figure 10/Z.102 below:

ccirr. 3 8so

FIGURE 10/Z. 102

## Example of a block interaction diagram

### 3.2.2 Relationship to the SDL abstract syntax

A block interaction diagram represents a block substructure definition. The definitions contained in the block substructure definitions are represented by the block and channel symbols together with signal definitions given in SDL/PR.

The same graphical conventions described for the interaction diagram, defined in Recommendation Z. 101 apply to the block interaction diagram.

In addition to this, it is often useful to describe several levels of block partitioning in one diagram. This is obtained by replacing a block symbol, in a diagram, by the block interaction diagram for that block. An example of this is given in Figure 11/Z. 102 below:


FIGURE 11/Z. 102

Example of a nested block interaction diagram
3.3 Process tree diagram

A process tree diagram describes the partitioning of a process into sub-processes and where these sub-processes are allocated.

### 3.3.1 Symbols

The symbols used to compose a process tree diagram are shown below in Figure 12/Z.102:

<name> | Process symbol |
| :--- |
| The symbol represents a process, whose |
| name should appear inside the symbol. |

| Allocation symbol |
| :--- |
| The comment symbol is used to indicate |
| where the process, or sub-process, is |
| allocated. The name in the comment |
| should be the name of the block to which |
| the process is allocated. |

FIGURE 12/Z. 102

Symbols used in process tree diagram

Each process is connected downwards to its sub-processes to form a hierarchical tree, as in Figure 13/Z. 102 below:


FIGURE 13/Z. 102

Example of a process tree diagram

### 3.3.2 Relationship to the SDL abstract syntax

The diagram represents a process substructure definition. The name in the root symbol is the associated process name, and the names in the leaf symbols are the contained sub-process names. The block names in the allocation symbols are the associated sub-block names.

### 3.3.3 Graphical conventions

The tree should preferably be drafted so that processes at the same partitioning level appear beside each other in the diagram.

If a processes tree diagram is large, it may be suitable to split the diagram into several diagrams. This splitting should be such that the first diagram is chopped off so that a set of further partitioned processes appears as not partitioned. In the following diagrams these processes appear as roots. For example, in Figure 14/Z.102 the diagram from Figure 12/Z. 102 is split into two diagrams.


FIGURE 14/Z. 102

Example of splitting a process tree diagram into several diagrams

This diagram represents the partitioning of a channel into sub-components. As the components are blocks and channels the diagram resembles a block interaction diagram.

### 3.4.1 Symbols

The symbols used to represent a channel substructure diagram are shown below in Figure 15/Z.102.


FIGURE 15/Z. 102

Symbols used in the channel substructure diagram

In addition to these symbols, signal definitions may appear in the diagram, using the SDL/PR syntax.
The rules for connecting the diagram are the same for the interaction diagram (see Recommendation Z.101), with the only exception that the title of the diagram should make it clear that the diagram is a channel substructure diagram.

A simple example of a channel substructure diagram is given in Figure 16/Z.102 below:

coit ineso

FIGURE 16/Z. 102
Example of a channel substructure diagram

### 3.4.2 Relationship to the SDL abstract syntax

A channel substructure diagram represents a channel substructure definition. The definitions contained in the channel substructure definition are represented by the block and channel symbols together with the definitions in $S D L / P R$ syntax.

The channel leading from the frame into the diagram represents the incoming channel and the channel terminating at the frame, represents the outgoing channel.

### 3.4.3 Graphical conventions

The same graphical conventions as described for the interaction diagram in Recommendation Z. 101 apply to the channel substructure diagram.

## 4 SDL/PR

The following SDL/PR syntax is an addition to the syntax defined in Recommendation Z.101. The additions cover the representation of the structure and partitioning of a system.

Note that in the examples, $S D L / P R$ keywords appear in capital letters.

### 4.1 Block definition

The block definition in $S D L / P R$ is extended to optionally include the non-terminal "Block substructure definition".

### 4.1.1 Syntax



FIGURE 17/Z. 102
Syntax diagram for block

## 4.2 <br> Block substructure definition

The block substructure definition represents the partitioning of a block into sub-blocks, sub-channels and new channels.

## BLOCK SUBSTRUCTURE DEFINITION



FIGURE 18/Z. 102

## Syntax diagram for block substructure diagram

## CHANNEL SPLITTING



## SUBBLOCK SPECIFICATION



CHANNEL SPECIFICATION


## SIGNAL SPECIFICATION



Example:

## BLOCK b:

SUBSTRUCTURE b;
SUBBLOCKS b1, b2, b3;
CHANNELS c1, c2, d1, d2, e;
SIGNALS s1, s2, s3;
SPLIT c INTO c1, c2;
SPLIT d INTO d1, d2;
/* Channel definitions */
/* Block definitions */
/* Signal definitions */

## ENDSUBSTRUCTURE;

ENDBLOCK b;

### 4.2.2 Relationship to the SDL abstract syntax

The syntax represents the block substructure definition and the internal part block definition in the abstract syntax. The names of blocks, signals and channels are references to the contained block definitions, signal definitions and channel definitions.

### 4.3 Process substructure

This syntax represents the partitioning of a process into sub-processes, and the allocation of these into sub-blocks. The partitioning may be shown both in the process definition and the block substructure definition.

THE PROCESS DEFINITION IS EXTENDED AS FOLLOWS:


THE PROCESS SUBSTRUCTURE DEFINITION IS A FOLLOWS:


The following example shows the process substructure as a part of a process definition:
Example:
SUBSTRUCTURE p 1 ;
p2 IN b2;
p3 IN b1;
ENDSUBSTRUCTURE;
ENDPROCESS p1;

The next example shows the process substructure as a part of a block substructure definition:

Example:

SUBSTRUCTURE b;
SUBSTRUCTURE p ;
p1 IN b2;
p2 IN b1;
ENDSUBSTRUCTURE

## ENDSUBSTRUCTURE;

ENDBLOCK b;

### 4.3.2 Relationship to the SDL abstract syntax

The syntax construction represents the process substructure definition in the abstract syntax. The associated process name is the name in the starting clause and the contained set of process names, each associated with a block name, are the names separated by the "IN" keyword.

### 4.4 Channel substructure

This syntax represents the partitioning of a channel into a set of channels and blocks.

### 4.4.1 Syntax

The syntax for a channel is extended to contain the non-terminal "channel substructure" as an optional part.

CHANNEL DEFINITION


FIGURE 19/Z.102 (1 of 4)

[^1]CHANNEL SUBSTRUCTURE DEFINITION


FIGURE 19/Z. 102 (2 of 4)

## Syntax diagrams for channel substructure

## INCOMING-OUTGOING CHANNELS



FIGURE 19/Z. 102 (3 of 4)

Syntax diagrams for channel substructure

## BLOCK SPECIFICATION



FIGURE 19/Z.102 (4 of 4)

Syntax diagrams for channel substructure

The channel substructure is a set of references to the components and additional definitions of the substructure.

## Example:

```
CHANNEL c FROM b TO d;
SUBSTRUCTURE
            INCOMING TO e;
            OUTGOING FROM f;
            BLOCKS: e,f;
            CHANNEL cl FROM e TO f WITH s1,s2,s3;
            BLOCK e;
            ENDBLOCK e;
            BLOCK f;
            ENDBLOCK f;
        ENDSUBSTRUCTURE;
```


### 4.4.2 Relationship to the SDL abstract syntax

The syntax represents the channel substructure definition in the abstract syntax. The block, channel, signal and data identifiers given in the syntax are references to the contained definitions.

## Recommendation Z. 103

## FUNCTIONAL EXTENSIONS TO SDL

## 1 <br> Introduction

This Recommendation defines a number of additional concepts and shorthand notations in the SDL. The basis for these additions are the basic SDL, as defined in the Recommendation Z.101. The intention with these additions is to provide the users of SDL with convenient concepts and shorthand notations.

The following concepts and shorthand notations are defined in this Recommendation:

## Procedures

These give a way to represent a portion of a process graph by one element, which may be referred to several times. The detailed behaviour of the procedure is defined elsewhere, inside or outside the process graph. Procedures may be used to support the use of structured-design methods with SDL, by permitting the decomposition of a process graph into a hierarchy of sections. The concept is similar to the procedure concept normally appearing in programming languages.

## Import and Export of values

This is a shorthand notation for the signal interworking between process instances when they are to share a value of a variable owned by one of the processes.

## Enabling condition

This is a shorthand notation to avoid «state explosion» when the reception or saving of a set of signals is conditional.

## Continuous signal

This is a shorthand notation to represent the signal interwork when a continuous condition, external to the process, is observed.

## Macro

This is a syntactic method for the user to define a shorthand notation. A macro is the definition of a composite syntax element in terms of other syntax elements already defined. A macro has no semantics of its own.

## Option

This is a syntactic facility to represent several, alternative behaviours in one diagram, or linear text. It has to be decided, before the diagram or linear text is interpreted, which alternative offered by an option should be chosen.

This Recommendation also defines an extension graphic syntax of SDL, that is the use of pictorial elements in state symbols.

## 2 <br> Procedures

A procedure is a means of giving a name to an assembly of items and representing this assembly by a single reference. The rules for procedures impose a discipline upon the way, in which the assembly of items is chosen, and limit the scope of the name of data items and signals.

Procedures are intended to:
a) permit the structuring of a process graph into several levels of detail;
b) maintaining the compactness of specifications by allowing a complex assembly of items which may be regarded in isolation to be represented by a single item;
c) allow commonly used assemblies of items to be pre-defined and used repeatedly.

Procedures are defined by means of procedure definitions. The procedure is invoked by means of a procedure call referencing to the procedure definition. Parameters are associated with a procedure call: these are used both to pass values, and also to control the scope of data and signals for the procedure execution. Which signals and data items are affected by the interpretation of a procedure is controlled by the parameter passing mechanism.

### 2.1 Common Language Model

The definitions following are to be considered strictly as additions to what is defined in the Recommendation Z.101.

### 2.1.1 An Introduction to the Common Model

A procedure is a section of a process graph which may be regarded in isolation. It has a single entry point and a single exit point. A procedure call may appear wherever a task may appear in a process graph or a procedure graph. A procedure may contain states. All data items used in a procedure must be defined within the procedure definition. If a data item is defined as a formal parameter, it uses values of data items in the calling environment and/or will give values to data items in the calling environment, otherwise the item is local to the procedure, and has to be defined in the procedure definition.

A procedure is interpreted only when a process instance calls it, and is interpreted by that process instance. When a procedure call is interpreted, the procedure graph must be interpreted before continuing the interpretation of the transition in which the call appears. This means that the calling process instance's input port and valid input signal set is used whilst interpreting the procedure. All signals referenced within a procedure must be named as formal parameters of the procedure. All signals in the valid input signal name set of the calling environment which
are not referenced within the procedure must also be named as parameters of the procedure, i.e. the additional-saveset. This allows the procedure to automatically save any other signals which may arrive in the input port. If this were not done the introduction into a transition of a procedure call to a procedure containing a state would have hidden side effects of losing signals (by implicit «null transitions») which arrived while a process instance was interpreting a procedure.

A procedure definition is given by a procedure graph, and may appear wherever a data type definition may appear.

A procedure graph follows the same rules as a process graph, with the following exceptions:

- a start node is replaced by a procedure start node;
- a stop node is replaced by a return node;
- only the data items, formal parameters and signal names which are declared within the procedure are visible to the process instance while interpreting the procedure, i.e. a procedure cannot refer to any data item or signal which is outside the procedure unless it is declared as a formal parameter (signals necessarily belong to the calling environment of the procedure, and all signals which are input, saved or output in the procedure must be declared);
- the same signal name actual parameter may not be mapped onto more than one signal name formal parameter;
- in the abstract syntax the set of signals to be saved is passed as parameters of the procedure call. However, in the concrete syntax, all state nodes contained within a procedure have an implicit save signal set containing all input signals which are not declared as formal parameters in the procedure.


### 2.1.2 Abstract Syntax

To the abstract syntax defined in Z .101 the following additions are made:

## System Definition

A system definition may also contain one or more procedure definitions.

## Block Definition

A block definition may also contain one or more procedure definitions.

## Process Definition

A process definition may also contain one or more procedure definitions.

## Process Graph

A process graph may also contain a procedure call node.
A transition string may also be a procedure call node followed by a transition string.
A procedure call node contains a procedure identifier and an actual parameter list.

## Procedure Definition

The procedure definition is associated with a procedure name and contains a formal parameter list, an additional-save-set, and a procedure graph, and may contain procedure definitions and data definitions.

The formal parameter list may be empty. Each formal parameter in the list must be attributed with one of the attributes IN, IN/OUT or SIGNAL.

The names of the formal parameters attributed with $I N$ or IN/OUT may not be used in variable definitions contained in the procedure definition; and the set of formal parameters names attributed with SIGNAL must contain all the signal names referenced in the procedure graph.

## Procedure Graph

A procedure graph is a graph whose nodes are connected by directed arcs. An arc entering a node is called an incoming arc and an arc exiting the node is called an outgoing arc. A node having an arc as incoming arc follows the node having the same arc as an outgoing arc.

The following types of nodes are allowed on a procedure graph:
State node
Input node
Task node
Output node

Decision node
Procedure Call node
Procedure Start node
Return node
Create Request node
Every node of the graph has a name and a type. State nodes within a procedure graph have different names.

The following rules define the connectivity of a procedure graph:

- Each procedure graph contains one and only one procedure start node. The procedure start node is followed by a transition string. The start node does not follow any other node.
- A transition string can be one of the following:
a) null followed by either a state node or a return node,
b) an action string followed by a transition string,
c) a decision node.
- An action string can be one of the following:
a) a task node,
b) an output node,
c) a create request node.
- A decision node is followed by two or more decision arcs.
- A decision arc is a named arc followed by a transition string.
- A state node is followed by one or more input nodes.
- An input node is followed by a transition string.
- The return node has no nodes following it.
- Each graph has at most one return node.
- Each node is reachable from the procedure start.

A call node contains a procedure identifier, an additional-save-list and an actual parameter list. In this list there must be one actual parameter for each of the formal parameters in the referenced procedure definition. Each actual parameter must match the type of the corresponding formal parameter. Any signal actual parameter name may not appear more than once in the actual parameter list.

Each actual parameter for which the corresponding formal parameter has the attribute $I N / O U T$ must be a variable name.

The additional-save-set is a possibly empty set of signal identifiers.

### 2.1.3 Interpretation

The following additions are made to the interpretation rules of Recommendation Z.101:

## Process

A call node is interpreted as the interpretation of the procedure start node of the procedure definition referenced by the name of the node, then the node following the call node is interpreted.

The additional-save-set is given the value of all signal identifiers in the valid input signal set of the calling process, which do not appear as actual parameters of the node.

## Procedure

When a process interprets a call node referencing the procedure definition containing the procedure graph, the procedure graph is interpreted. The nodes of the procedure graph are interpreted in the same manner as the equivalent nodes of the process graph, with the following exceptions and additions:

- Each formal parameter attributed with IN denotes a typed variable. This variable is local to the procedure and is created when the procedure start node is interpreted and ceases to exist when the return node is interpreted.
- Each formal parameter attributed with IN/OUT denotes a synonym name for the variable which is given as actual parameter. This synonym name is used throughout the interpretation of the procedure graph when referring to the value of the variable or when assigning a new value to the variable.


## Procedure start node

The interpretation of a procedure start node involves:

- A local variable is created for each formal parameter attributed with IN, having the name and data type of the formal parameter. The variable is assigned the value of the actual parameter, which may be undefined.
- Each variable name given in the formal parameters attributed with IN/OUT is used as a synonym name for the variable name given as actual parameter. The variable represented by the synonym name is evaluated once only at the procedure start node, and not at each use of the formal parameter in the procedure.
- Each signal name given in the formal parameters attributed with SIGNAL is used as a synonym name for the signal identifier given as actual parameter.
- The node following the procedure start node is interpreted.


## State node

The state node is interpreted in the same way as in a process graph with the exception that the save-signal-set presented to the input port is union of the additional-save-set and the save-signal-set of the process or procedure which called the current procedure.

### 2.2 SDL/GR

The addition of the procedure concept into SDL causes the addition of one new symbol in the process diagram: the call symbol.

The procedure definition, is in the graphic syntax represented by a procedure diagram. This diagram is similar to the process diagram, except for the procedure start symbol and the return symbol.

In the following only the additions, required by introducing procedure, to the graphic syntax as defined in Recommendation Z.101, are given.

### 2.2.1 Process diagram

### 2.2.1.1 Symbols

The following symbol is used to represent the procedure call:


The symbol may appear in a process diagram wherever a task symbol is allowed.

The procedure name and the actual parameters are given using the SDL/PR syntax.

FIGURE 1/Z. 103
The procedure call symbol
2.2.1.2 Relationship to the SDL abstract syntax

The procedure call symbol represents the procedure call node in a process graph.
The actual parameters given in the symbols represents the actual parameters attached to the procedure call node. Any valid input signal not given as actual parameter is a member of the additional-save-set for the procedure call node, denoting that that signal should be saved throughout the procedure execution.

## Return node

The interpretation of the return node involves:

- all variables created by the interpretation of the procedure start node will cease to exist;
- all synonym names established by the interpretation of the procedure start node will cease to exist;
- interpreting the return node completes the interpretation of the procedure start node.


### 2.2.2 Procedure diagram

A procedure diagram is similar to a process diagram, the only differences being that the start symbol is replaced by the procedure start symbol, and the stop symbol is replaced by the return symbol.

In the following only the additional syntax is defined.

### 2.2.2.1 Symbols

In Figure 2/Z. 103 below two additional symbols are defined:


FIGURE 2/Z. 103

Additional symbols for procedure diagram

### 2.2.2.2 Relationship to the SDL abstract syntax

The procedure diagram represents the procedure definition in the SDL abstract syntax.
The symbols common with the process diagram have the same relations to the abstract syntax as when appearing in a process diagram. The additional procedure start symbol and the return symbol represent respectively the procedure start node and the return node.

The parameters attached to the procedure start symbol represents the formal parameters attached to the procedure start node.

### 2.2.2.3 Graphical conventions

Generally the same graphic conventions as for the process diagram apply. The conventions for the procedure start symbol and for the return symbol are the same as for the process start symbol and the stop symbol respectively.

Wherever a return symbol appears it represents the return node (multiple appearance of a return symbol).

## 2.3 $S D L / P R$

$S D L / P R$ syntax for a procedure definition is given below. The procedure definition may appear wherever a data type definition may appear in the syntax. The syntax is similar to that of the process definition.

Below is given only the additions to the syntax already defined in Recommendation Z.101.

### 2.3.1 System

### 2.3.1.1 Syntax

The syntax of procedure definitions is added to the syntax of system:

## SYSTEM DEFINITION



FIGURE 3/Z. 103

Syntax diagram for system

### 2.3.2.1 Syntax

The syntax of procedure definitions is added to the syntax of block:


FIGURE 4/Z. 103

Syntax diagram for block

### 2.3.3.1 Syntax

The syntax of procedure definition is added to the syntax of process, and the syntax of procedure call is added to the syntax of a transition string:


FIGURE 5/Z. 103
Syntax diagram for process


FIGURE 6/Z. 103 (1 of 2 )

Syntax diagram for action

## PROCEDURE CALL



FIGURE 6/Z.103 (2 of 2)

Syntax diagram for procedure call

The procedure call in a transition represents the call node in the abstract syntax, and the actual parameters represent the actual parameters attached to the call node.

Each actual parameter given has to conform with the data type of the corresponding formal parameter in the referenced procedure definition.

### 2.3.4 Procedure

2.3.4.1 Syntax

PROCEDURE DEFINITION


FIGURE 7/Z. 103 (1 of 5)
Syntax diagrams for procedure


FIGURE 7/Z. 103 (2 of 5)

Syntax diagrams for procedure

## PROCEDURE VARIABLE DEFINITION



FIGURE 7/Z. 103 (3 of 5)

Syntax diagrams for procedure

PROCEDURE BODY


FIGURE 7/Z. 103 (4 of 5)
Syntax diagrams for procedure

## TERMINATOR



FIGURE 7/Z.103 (5 of 5 )

Syntax diagrams for procedure

### 2.3.4.2 Relationship to the SDL abstract syntax

The procedure syntax diagram represents the procedure definition of the abstract syntax. The formal parameters in the syntax diagram represent the formal parameters attached to the procedure start node.

The syntactic constructs allowed within a procedure and common with those allowed in a process have the same relations to the abstract syntax as when they appear in a process. The procedure start node is implied and is followed by the first syntactic construct of the procedure, and the return statements, represent the return node.

A composite operation is a standard shorthand notation for assemblies of SDL concepts. The composite operations are defined in terms of already present SDL concepts and do not add to the semantics of the language. Thus they do not change the abstract syntax on its interpretation. They are introduced for the convenience of the users of SDL.

The composite operations defined here provide some alternative methods of communication between SDL process instances. While they appear significantly different from the normal signal exchange mechanism of SDL to the user, they are in fact based upon the normal SDL semantics.

The composite operations provide:
a) sharing values of data items between processes, even if they are allocated in different blocks;
b) the capacity to temporarily enable or disable the reception of particular signals without the need to show this exactly with separate states;
c) continuous signals, for which transitions are caused by a change of a value of the signal.

Each of the composite operations is given a syntax of its own and are defined in terms of "normal" SDL concepts. Thus the composite operations involve for the user implied or hidden states, signals and procedures. The composite operations are defined in $\S \S 3.1$ to 3.3 using illustrative names for the normal SDL symbols. When any composite operation is used in an SDL representation, the implied SDL symbols have unique implied names. These implied names are so chosen that there are no clashes between different occurrences of the composite operation or other names in the SDL representation. The SDL user is thus free to employ these names for other purposes should he wish to do so.

As the composite operations are defined in other SDL terms they may in some situations lead to side effects, these are discussed in the SDL User Guidelines.

### 3.1 Imported and exported values

In SDL a variable is always owned by, and local to, a process instance. Normally the variable is visible only to the process instance which owns it, though it may be declared as a shared value (see Recommendation Z .101 ) which allows other process instances in the same block to view the value of the variable. If a process instance in another block needs to view a variable, a signal interchange with the process instance owning the variable is needed.

The following paragraphs describe a standard method, and a shorthand notation for doing this. The technique will be called imported values, since communication is by means of copies of the value of the variable, only the owning process instance having access to the variable itself. The technique may also be used to export values to other process instances within the same block, in which case it provides an alternative to the use of shared values. This alternative is necessary when either it is likely that the block will be decomposed such that the process instances concerned are in different sub-blocks or when the values are used in enabling conditions (see § 3.3).

The process instance which owns a variable whose values are made available to other process instances is called the exporter of the variable. Other process instances which use the variable are known as importers of the variable.

Access to the value of the variable is obtained by an exchange of signals. The importer sends a signal to the exporter, and waits for the reply. In response to this signal the exporter sends a signal back to the importer with the value the variable had when the last export operation was made.

The variables whose values are imported and exported are defined as such in their variable definitions. These variables are also identified by definitions in the channels carrying the implied signal interchange.

The definition of a variable as exported produces an implicit definition of a copy of it to be used in the import and export operations.

The process instance discloses the value of a variable defined as exported by means of the statement:
EXPORT (x) where x is the name of the variable.
The EXPORT ( x ) causes the storing of the current value of x into the implicit copy and the sending of signals to process instances awaiting an enabling condition (§ 3.2) or continuous signals (§ 3.3).

The EXPORT operation can be made in conjunction with the manipulation of the variable or independently of it, e.g:

EXPORT (x): = <expression>;
or
EXPORT (x);

The construct may only appear in a task.
The access from another instance may only be done by means of the syntactic construct:
$\operatorname{IMPORT}(\mathrm{x}, \operatorname{Pid})$ where x is the name of the variable, and Pid is a reference to the owning process instance.

This construct may appear in a task and in a decisions.

### 3.1.1 Definition

### 3.1.1.1 Import operation by importer

The import operation is modelled in the importer's process graph by the following sequence of nodes :

- an output node, by name XQUERY, carrying a reference to the name of the variable whose value should be accessed, and addressed to the process instance which owns the variable (the exporter);
- a state node with a save signal set including all signals except XREPLY;
- an input node for the signal XREPLY returning the value of the value of the requested variable;
- an implicit variable of the same type as the exported variable is assigned the value associated to the XREPLY signal. This implicit variable name replaces the import operation. At each occurrence of the construct operation, a new implicit variable is used.

The sequence of operations defining the import operation is explained below using the graphic SDL syntax. The IMPORT(x,pid) statement will correspond to the following transition string.


Note - This diagram is explanatory. A user of the import operation would only write: IMPORT (x, pid).

FIGURE 8/Z. 103

Import operation explained in SDL/GR

### 3.1.1.2 Import operation by the exporter

As the import operation implies actions performed by the exporter the following implied transition is added to every state of the exporter (including all implicit states):

- an input node for the signal XQUERY;
- an output node by the name XREPLY, returning the value implicit copy of the requested variable to the requesting process instance;
- a return to the state from which the transition originated.
(It should be noted that the exporter is also modified with other transitions if the exported values are used in enabling conditions and/or continuous signals, see $\S \S 3.2$ and 3.3.)

The implied transition using the graphical syntax of SDL is shown in Figure 9/Z.103.

cc17-73920
Note - This diagram is explanatory only. Since the transition is implied the user does not write anything.

FIGURE 9/Z. 103

Import operation by the exporter explained in SDL/GR

### 3.1.1.3 Export operation

The export operation is the means by which the owner of an exported variable disclose to importers the current value of the variable. As a result of the export operation, the implicit copy of the variable is given the current value of the variable. In the absence of enabling conditions or continuous signals the operation itself is modelled as a task node, assigning the value to the variable. However, the export operation interacts with the models for enabling condition and for continuous signal, see $\S \S 3.2$ and 3.3.

### 3.1.2 Rules for using imported values

- All imported values must be defined as IMPORTED in the importer and as EXPORTED in the exporter. The export attribute in a variable definition makes the variable identifier visible throughout the system.
- The source and destination of the import operation is shown by including the name of the imported value in a signal list attached to a channel or to a signal path within a block. The source and destination may be in different blocks or in the same block.
- A process instance which imports values may also export values, but it must not import values of its own variables.
- An imported value <name> is imported by using the statement:

IMPORT (<name>, < pid>)
in a task, decision or enabling condition. The <name> is the name of the imported item and the <pid> is the process instance identifier of the owning process instance. All other references in the process to <name> will be interpreted as references to the local copy of the value of <name>.

- The disclosure of the value of an exported variable is made through the statement:
$\operatorname{EXPORT}(<$ name > ):= <expression >
or
EXPORT (<name>)
contained in a task.

Imported values are referenced at three points in process definition. The syntax for these is the same in both the $S D L / P R$ and the $S D L / G R$.
3.1.3.1 In variable definitions and import definitions the keywords IMPORTED and EXPORTED identify the use to be made of the declared variable.

## VARIABLE DEFINITION



FIGURE 10/Z. 103 (1 of 2)
Syntax diagram for variable definition and import definition

## IMPORT DEFINITION



FIGURE 10/Z. 103 (2 of 2 )
Syntax diagram for variable definition and import definition
3.1.3.2 In signal lists in SDL/GR an imported value is distinguished from a signal by enclosing the name of the imported value in round brackets.
$\left[\begin{array}{l}\text { Signal-name-1 } \\ \text { (Variable name) } \\ \text { Signal-name-2 }\end{array}\right]$

## CHANNEL DEFINITION



FIGURE 11/Z. 103 (1 of 2)
Syntax diagram for channel definition and variable list

## VARIABLE LIST



FIGURE 11/Z.103 (2 of 2)
Syntax diagram for channel definition and variable list

## STATEMENT



FIGURE 12/Z. 103 (1 of 3 )
Syntax diagram for export statement

## EXPORT STATEMENT



FIGURE 12/Z.103 (2 of 3)

## Syntax diagram for export statement

## EXPORT OPERATOR



FIGURE 12/Z. 103 (3 of 3 )

## Syntax diagram for export statement

## IMPORT OPERATOR



FIGURE 13/Z. 103

Syntax diagram for import statement

### 3.2 Enabling condition

A reduction in the number of states in a process graph can often be achieved by having means of attaching conditions to the commencement of transitions. The conditions are assertions involving variable, and are known as enabling conditions. If the condition is true and the associated input signal is retained, the transition proceeds normally. If the enabling condition is not true, the transition is inhibited and the input signal is instead saved.

In normal SDL such conditional execution of transitions would need to be modelled with separate states for each value of the enabling condition. The concise notation provided by enabling conditions is useful in simplifying a process graph.

Enabling conditions may be expressed using both local and/or imported values. Shared values must not be used.

The enabling condition is described in terms of basic SDL concepts (see Recommendation Z.101). An enabling condition is used in a process graph and is attached to an input symbol or an input statement. It is an assertion involving data values which are either local or imported values. The condition must be a Boolean expression, hence returning the values TRUE or FALSE. Each state which is followed by transitions controlled by enabling conditions in fact represents a set of states, one for each possible combination of the enabling condition. The conditions are evaluated before one of the appropiate member of the set of states is selected as the next state.

The interpretation of an enabling condition depends on the data values used in the condition. If an enabling condition contains only values which are local to the process it needs only to be evaluated once. If it contains imported values (see § 3.1), the condition must be evaluated each time one of the imported values changes: the evaluation is invoked by implied signal interchange between the importer and exporter(s) of the values.

Enabling conditions which use imported values make use of further hidden signals, in addition to the XQUERY defined in § 3.1, which are XATTACH and ZDETACH. These are requests for the exporter to add or remove the importer from a list of those process instances which need to be informed of changes in the exported value. The exporter maintains such an implicit list, XLIST, for each value it exports. A further signal, XWAKE, is sent by the exporter to each member of the list whenever it makes an export operation on the corresponding data item.

### 3.2.1 Definition

### 3.2.1.1 Single enabling condition based on local values

When only one of the inputs following a state has an attached enabling condition, and that condition contains only local values, the interpretation is as follows.

The state, the following inputs and saves are replaced by:

- a decision node which evaluates the enabling condition;
- the "TRUE" branch of the decision is followed by a state node with the same save-signal-set as the original state and followed by the same set of inputs as the original state (the input to which an enabling condition was attached appears as an input node);
- the "FALSE" branch of the decision is followed by a state node having the save-signal-set of the original state extended with the signal name of the input having the enabling condition attached;
- each of the input nodes are followed by the same transitions as in the original graph.

In the following figure the definition of the Simple Enabling Condition based on local values only are shown using the graphic syntax of SDL:

Note - The user writes this:


FIGURE 14/Z. 103

Single enabling condition using local values only explained in SDL/GR

### 3.2.1.2 Single enabling condition containing imported values

When only one of the inputs following a state has an attached enabling condition, which contains at least one imported value, the interpretation will lead to an implied signal interchange with the owners of the imported values.

As the variables holding the imported values are handled by other process instances, working concurrently, the value of the enabling condition may change while the process instance is waiting in a state. Any such change should lead to a new evaluation of the condition. When entering an enabling condition construct the owners of the imported values are informed that this instance should be notified if any changes of the value occurs. Thus when an imported value is changed also a signal is sent to all processes that need informing, so that they evaluate the conditions again.

The definition is as follows:
The valid input signal set of the process which contains the enabling condition is extended by the implicit signal XWAKE. The state and the set of inputs and saves following it are replaced by:

- a sequence of output nodes for the signal XATTACH (one for each of the imported values used in the enabling condition);
- the attach sequence is followed by a decision and two state nodes, as in § 3.2.1.1;
- the decision, because it contains imported values, is itself expanded as in §3.1.1.2, so that it is preceded by import operations for each imported value it uses;
- in addition to the expansion defined in §3.2.1.1 the two state nodes are also followed by an input node for the signal XWAKE, with the following transition leading back to the decision evaluating the condition;
- also in addition to the expansion defined in §3.2.1.1 each input node, except for the XWAKE, are followed by a sequence of output nodes for the signal XDETACH (one for each of the imported values used in the enabling condition) and the sequence is then followed by the same transition as in the original construct.

Note - The user draws this:


FIGURE 15/Z. 103

Single enabling condition using imported values explained using SDL/GR

### 3.2.1.3 Actions by the exporter when imported values are used in enabling conditions

When an exported value is used in an enabling condition the exporter has the following implied properties in addition to those defined in $\S \S 3.1 .1 .2$ and 3.1.1.3.

To invoke the revaluation of enabling conditions using imported values the exporter implicitly maintains a list, XLIST, of process instances to be informed if the values change. Process instances will enter that list by sending the signal XATTACH, and will remove themselves from the list by sending the signal XDETACH.

Whenever a new value is exported by means of the export operation all process instances in the XLIST will be informed of this new value by the signal XWAKE.

The definitions of the addition are:
Each process which exports values is extended by:
a) adding the implicit signals XATTACH and XDETACH to the valid input signal set;
b) defining a list XLIST. < name> for each value which is exported. The lists will hold process instance identifiers.

To each state of the process, including all implied states, is added two implied transitions, in addition to the implied transition defined in § 3.1.1.2. The first of these transitions consists of:

- an input node for the signal XATTACH;
- a task which adds the process instance identifier of the sender of the signal XATTACH to the XLIST corresponding to the variable nominated in the signal; whose value is exported;
- a return to the state from which the transition originated.

The second implied transition consists of:

- an input node for the signal XDETACH;
- a task which removes the process instance identifier of the sender of the signal XDETACH from the XLIST nominated in the signal;
- a return to the state from which the transition originated.

The additional implied transitions of each state of the exporter is shown below using the graphical syntax of SDL:


Note - This diagram is for explanatory purpose only. All transitions are implied.

FIGURE 16/Z. 103

## Implied transitions of the exporting process explained in SDL/GR

The following implied transition is added to the definition of the export operation, § 3.1.1.3:

- following a task including an export operation is a sequence of output nodes for the signal XWAKE conveying the disclosed value. There will be one XWAKE signal sent to each process instance currently included in the XLIST for the corresponding variable which was disclosed the value.

The addition to the export operation is shown below using the graphic syntax of SDL:
The user writes:


Note - This diagram is for explanatory purpose only.

FIGURE 17/Z. 103
Implied actions by the export operation explained in SDL/GR

### 3.2.1.4 Multiple enabling conditions

Having several enabling conditions following a state is known as multiple enabling conditions.
If n of the inputs nodes following a state have enabling conditions attached to them, then the definitions of single enabling conditions will be extended as:
a) the state and the following inputs and saves are represented by a decision node for a complex condition whose value is an n-tuple with elements the value of the elementary enabling conditions. This is followed by $2 * *$ n state nodes, each followed by the transition processing which is appropiate to the particular values of the enabling conditions which named the arc leading to that state node;
b) if any of the enabling conditions refer to imported values, the definitions in § 3.2.1.2 also applies.

The user writes this:


FIGURE 18/Z.103

Multiple enabling conditions explained using the SDL/GR

1) Enabling conditions may be attached to any input signal.
2) There may be only one input following a state containing a given input signal, regardless of whether or not the input has an enabling condition attached.

Concrete syntax

### 3.2.3.1 $S D L / G R$

Enabling conditions are shown in the $S D L / G R$ by an enabling conditions symbol following an input symbol. The element is a pair of angle brackets embracing a Boolean condition. The graphical syntax is shown in Figure 19/Z.103:


FIGURE 19/Z. 103

SDL/GR syntax for the enabling condition


FIGURE 20/Z. 103

Example of use of SDL/GR enabling condition syntax

In $S D L / P R$ the syntax of the input statement is modified by adding the PROVIDED phrase. The PROVIDED phrase contains a Boolean expression. The syntax diagram for the modified input statement is given in Figure 21/Z.103:

STATE BODY


FIGURE 21/Z.103 (1 of 2)

Syntax diagram for the input statement including the PROVIDED phrase

## ENABLING CONDITION



FIGURE 21/Z.103 (2 of 2)

## Syntax diagram for the input statement including the PROVIDED phrase

In describing systems with SDL, the situation frequently arises where a user would like to show a transition as being caused by a change in the value of a variable external to the process. The value might, as an example be a high or low voltage on a line or a number in a status register. The normal way to achieve this in SDL would be to arrange that a signal is generated when the change in the value occurs and to base the transition upon the reception of that signal. The necessity to explicitly define, generate and receive such signals may complicate the process graphs. The composite operation known as a continuous signal allows a change in the value of a condition to directly initiate a transition.

An enabling condition represents a decision before entry to a state. When imported values are used the enabling conditions provides exits from a state by means of the implicit XWAKE signal. It may also be used without an associated input signal when it becomes a continuous signal. In this case, the enabling condition does not represent an extra, implied state but instead defines a circumstance in which there is an escape from the state from which the enabling condition follows. This circumstance has a priority lower than the retained signals.

Several continuous signals may lead from the same state and these may be such that more than one is true at the same time. Each continuous signal is associated with a priority which determines the relative order in which continuous signals are tested.

A continuous signal which uses only local values gives a means of conditionally exiting from a state if no signals are waiting in the input port at the time of entry. A continuous signal which uses imported values adds to this the capacity to revaluate the condition when there is a change in one of the imported values used in the condition.

### 3.3.1 Definition

The following definition is based upon the definitions of import and export of values, see § 3.1, and enabling conditions, see § 3.2.

The interpretation of a state which is followed by continuous signals is presented as a general model in which there are several continuous signals which collectively reference several imported values. If there are no imported values used, the model is simplified by the elimination of XATTACH and XDETACH outputs and the XWAKE input.

The state and the set of inputs and saves following it, together with the continuous signals are replaced by:

1) a sequence of output nodes for the signal XATTACH, one for each of the imported values used in the continuous signal condition;
2) a task which creates a unique value to be used in the EMPTYQ signal, used in 3);
3) an output node for a signal EMPTYQ which is sent to the process instance identity of the sender, i.e. to its own input port;
4) a state node as in the original process graph or procedure graph, followed by a set of input nodes which includes the original set and two other input nodes;
5) each input node is followed by a sequence of output nodes for the signal XDETACH, one for each of the imported values used in the continuous signal conditions. This sequence is then followed by the transition processing which originally followed the input node;
6) the state node in 4) is also followed by an input node for the signal XWAKE, this initiates the transition in 7);
7) a sequence of task nodes to import each of the imported values used in the continuous signal conditions;
8) a sequence of decision nodes for each of the continuous signal conditions, the first decision evaluated being that for the highest priority continuous signal (the lowest number in the concrete syntax);
9) the FALSE branch of each decision leads to a decision node for the continuous signal condition of next lower priority. The FALSE branch of the lowest priority continuous signal decision leads back to the state in 4);
10) the TRUE branch of each decision leads to a sequence of output nodes for the signal XDETACH, one for each of the imported values used in the continuous signal conditions, followed by the transition processing corresponding to the continuous signal condition tested in the decision;
11) the state node in 4) is also followed by an input node for the signal EMPTYQ, in turn followed by a decision node which tests that the signal carries the value given to it in 2), i.e. that it is the same signal sent in 3), and not an earlier, unprocessed EMPTYQ signal. The TRUE branch of this decision leads to the continuous signal processing in 7), and the FALSE branch leads back to the state node of 4).

The valid input signal set of the process containing continuous signals using imported values is extended by the implicit signal XWAKE. The valid input signal sets of any process containing continuous signals are extended by the implicit signal EMPTYQ.

The user writes this:


Note - This diagram is for explanatory purposes only.

FIGURE 22/Z. 103

## Continuous signal explained in SDL/GR

3.3.2 Rules for using continuous signals

1) Continuous signal may follow any state.
2) Continuous signal condition may be based on local values and/or imported values.
3) No two continuous signals following the same state may have the same priority number.

### 3.3.3.1 $S D L / G R$

In $S D L / G R$ a continuous signal is indicated by an enabling condition symbol which directly follows a state symbol, i.e. the transition is not headed by an input symbol. The symbol contains, as well as the continuous signal condition, the keyword PRIORITY followed by a priority number (natural number). The smaller the number, the higher is the priority of the continuous signal.


FIGURE 23/Z. 103
SDL/GR symbol for the continuous signal


FIGURE 24/Z. 103

## Example of the use of SDL/GR continuous signal

If only one continuous signal is following a state, the PRIORITY clause may be omitted. If the clause is omitted the priority number " 1 " is implied.

### 3.3.3.2 $S D L / P R$

In $S D L / P R$ a PROVIDED statement, followed by a transition string, represents the continuous signal. The statement contains a PRIORITY clause. The smaller the number, in the PRIORITY clause, the higher is the priority of the continuous signal.

CONTINUOUS SIGNAL


FIGURE 25/Z. 103

## Syntax diagram for continuous signal

## Macros

A Macro is a shorthand notation, defined by the user, that can be included in one or more places in the concrete SDL representation of a system. It represents a reference to a definition in a document elsewhere. A macro is only a part of the concrete syntax, and has to be substituted by the body of its definition in order to interpret the SDL representation in which it appears.

### 4.1 Definition

A macro may represent any collection of syntactic items, however, it may not be recursive for obvious reasons (infinite expansion!).

The macro can have zero or more inlets and zero or more outlets. In case of more than one inlet there should be a label attached to each inlet corresponding to the inlet label in the macro definition, in case of a single inlet the label may be omitted. The same applies for the outlets.

There is no scope or visibility associated to the macro concept as such. The interpretation of a macro reference may only be obtained when the macro is substituted by its definition.

### 4.2 Concrete syntax

4.2.1 $S D L / G R$

### 4.2.1.1 Syntax

The reference to a macro definition is shown by the macro symbol in the $S D L / G R$.


FIGURE 26/Z. 103
The macro symbol in SDL/GR
The inlets to and outlets from the macro is represented by flow lines leading to/from the symbol. Labels may optionally be attached to the flow lines.

The macro symbol contains the name of the macro definition it refers to, and a comment may be attached to the symbol.

The macro definition is entitled:
< name > MACRO DEFINITION
where the <name> is the name of the macro, and which is used in a macro symbol.
The macro definition contains the graphical representation which replaces the macro symbol before interpretation takes place. The inlets to and the outlets from the definition are represented by flow lines leading to and from the symbols in the definition respectively. Both the inlets and the outlets may have labels attached to them.

### 4.2.1.2 Symbols

In Figure 27/Z. 103 two additional symbols are defined:


FIGURE 27/Z. 103
Additional symbols for macro

The macro symbol may be inserted at any place in a diagram, and may represent any collection $S D L / G R$ symbols.

There must be the same number of inlets in a macro symbol as there are inlets in the referenced macro definition. The set of labels on the inlets in the macro symbol must be the same as the set of labels on the inlets in the macro definition. The same rule applies for outlets and outlet labels.

Inlets/outlets may terminate/originate from any side of the symbol.
As the semantic of a macro is obtained by substituting the reference by the collection of symbols in the definition, all graphic conventions apply to the diagram in which all macro appearances have been substituted. This may lead to unexpected consequences due to rules as for example the multiple appearance of states. This is further discussed in the SDL User Guidelines.

### 4.2.2 $S D L / P R$

### 4.2.2.1 Syntax

The macro call can be put in any diagram using the syntax:
MACRO macro name;
The macro expansion is a piece of an SDL/PR program starting with:
MACRO EXPANSION macro name;
and ending with:

## ENDMACRO macro name;

in the last statement, the macroname is not mandatory.
This definition must be placed immediately after the SYSTEM, BLOCK or PROCESS construct respectively depending on where the macro is referenced. The macro definition may contain any character and its correctness can only be evaluated after it has replaced the macro statement.

### 4.2.2.2 Rules for using macros in the $S D L / P R$

The same rules and concerns as when macros are used in the $S D L / G R$ also applies for the $S D L / P R$.

## Options

When several similar applications are specified or described using SDL often the same process definition can be used in the different systems if it is slightly modified. The OPTION facility in SDL provides means for defining processes generic for several applications by introducing alternative optional parts of the descriptions.

### 5.1 Definition

An option is the selection of alternative parts of a process definition, according to the evaluation of an option expression. The selection is made before the process definition is interpreted.

The option facility is only part of the concrete syntax, and should be considered as a shorthand notation providing one generic description for several applications rather than having one specific description for each application.

Concrete syntax
5.2.1 $S D L / G R$

### 5.2.1.1 Symbols

The following symbol is used in the $S D L / G R$ to represent option:


FIGURE 28/Z. 103

## The option symbol in SDL/GR

### 5.2.1.2 Rules for using options in the SDL/GR

The option symbol may follow a task symbol, a decision symbol outlet, an output symbol or a procedure symbol in a process diagram. The option symbol may be followed by a state symbol, a task symbol, a decision symbol, an output symbol or a procedure symbol.

The <option expression > contained in the symbol is an expression such that one of the <option alternative> following the symbol is uniquely chosen after evaluation, and such that it can be evaluated before interpreting the process. Each option alternative must be a value of the same type as the option expression. When the resulting process is interpreted the unreachable parts of the process definition should be considered as deleted.

### 5.2.2 $S D L / P R$

### 5.2.2.1 Syntax

The option is represented in the $S D L / P R$ by the following syntax:

## OPTION



FIGURE 29/Z. 103

The <option expression > contained in the statement is an expression such that one of the <option alternative $>\mathrm{s}$ can be uniquely chosen after evaluation, and such that it is evaluated before interpreting of the process. Each option alternative must be a value of the same type as the option expression. When the resulting process is interpreted the unreachable parts of the process definition should be considered as deleted.

## 6 Pictorial elements in SDL/GR

When the graphical syntax of SDL is used to represent process definitions the use of pictorial elements to form a state picture within a state symbol is an optional part of the $S D L / G R$.

Such state pictures can provide advantages when applied to certain system definitions, resulting in more compact and less verbal process diagrams. The state picture describes, in terms of pictorial elements and qualifying text, the actual status of the process when in that state. Also the assumed status of the environment of the process may be described in the state picture. When using state pictures the actions to be performed in transitions between the states is implied, by the difference of the described status.

When using pictorial elements, the syntax and semantics as defined elsewhere in the Recommendation Z. 101 apply. However, these semantics and syntax are extended as defined in the following.

### 6.1 Semantics of state pictures

When using pictorial elements a state node is represented by a state symbol. The state symbol is identified by its name, and contains a state picture consisting of pictorial elements, values of variables, input variables and qualifying text.

A state picture can represent:

1) using pictorial elements and qualifying text, the values, in that state, in a selected subset of the total set of variables associated with that process. The selected subset may include variables which serves purely as proxy for variables associated with other processes. These "proxy" variables carry the value of variables associated with other processes. These values are obtained either by viewing or importing the value;
2) using the values of input variables, the input actions with respect to the valid input signals for that state.
The repertoire of pictorial elements is in principle unlimited, since new pictorial elements can be invented to suit any new application of the SDL. However, in applications to telecommunications switching and signalling functions, the following repertoire of pictorial elements has been found to have considerable versatility:

- process boundary (left or right),
- terminal equipment (various),
- signalling receiver,
- signalling sender,
- combined signalling sender and receiver,
- timer supervision process,
- switching path (connected, reserved),
- switching module,
- charging in progress,
- control element,
- uncertainty symbol.

Standard symbols for these pictorial elements are recommended in $\S 6.3$.

### 6.2 Rules of interpretation

1) Input variables are Boolean variables and each input variable corresponds to one and only one signal from the set of valid input signals for the process. A change in the value of an input variable between state pictures always represents the consumption of a signal by an input of a process. Therefore, input variables can be used to represent those conditions of a process which, if changed, will result in the process performing a transition. The values of an input variable can be associated with pictorial elements.
2) The presence of pictorial elements in a state picture indicates specific values for a subset of variables while that process is in that state. The values of additional variables, particularly ones associated with this initial subset can be indicated by the qualification of the pictorial elements by qualifying text. Qualifying text is not an input variable; changes in the qualifying text DO NOT represent the consumption of an input signal by an input action of the process.
3) Positioning:
a) The positioning of any pictorial elements (other than a process boundary) relative to a process boundary determines whether the pictorial elements is "internal" or "external" to the process. An internal pictorial elements represents variables which are owned by the process. An external pictorial element represents variables which are owned by another process so that the viewing and import mechanisms must be used to access these variables.
b) Rule a) also applies to the distinction between internal and external qualifying text, by substituting the term "qualifying text" for pictorial elements in this rule.
4) Cardinal rule:

The total processing involved when going from one state to the following state is that required to effect the changes in the state pictures, together with the processing indicated in any decisions, outputs or tasks appearing in the transition between the states. Thus:
a) The change from the appearance of an internal pictorial element in one state to the absence of that pictorial element in the following state, or vice versa, corresponds to a change in the values of some variables which can be equivalently represented by the use of a task in the transition between the states.
b) The change from the appearance of an external pictorial element in one state to the absence of that pictorial element in the following state, or vice versa, corresponds to a change in variables owned by another process. This change can be equivalently represented either by an output signal to that other process or simply by the input signal from that process.
c) Rules (a) and (b) also apply to the appearance or disappearance in the state picture of qualifying text, by substituting the term "qualifying text" for pictorial elements in those rules.
5) For a given process diagram, particular pictorial elements (or a particular combination of pictorial elements and qualifying text) is positioned uniquely within the state picture so that the presence or absence of this pictorial element (or combination) in a state symbol can be quickly determined by comparing the state picture with other state pictures in the process diagram.
6) When a signalling sender appears in a state picture, its qualifying text identifies a signal which has been output prior to, or (in the case of a continuous signal controlled by the process) prior to and during this state.

### 6.3 Recommended symbols for pictorial elements

When using pictorial elements, each state is represented by a state symbol containing a state picture with the format shown in Figure 30/Z.103:

A basic set of pictorial elements has been standardized for use in the $S D L / G R$ with application to the system description of telecommunications call handling processes, including signalling protocols, network services and signalling interworking processes. Many of these pictorial elements are capable of being applied in applications of the $S D L / G R$ beyond call handling processes, and their application to other processes in telecommunications, where appropriate, is encouraged.

The recommended symbols for the basic set of pictorial elements is shown in Figure 31/Z. 103 below:
The choice of pictures for pictorial elements has been based upon the considerations and general selection criteria presented in Annex A to this Recommendation, which should be consulted before developing additional pictorial element symbols for wider applications of the $S D L / G R$.

The recommended proportions for pictorial element symbols are shown in Annex B to this Recommendation.

The template which is enclosed in the inside back cover of this fascicle and which is suitable for hand drawing the basic set of $S D L / G R$ symbols, includes in this basic set the pictorial element symbols shown in Figure 31/Z.103.


FIGURE 30/Z. 103

Recommended format of a state symbol with state picture

| 1) Functional block boundary |  | L | 4) Signalling receiver |  |
| :---: | :---: | :---: | :---: | :---: |
| 2) Terminal equipment | (a) telephone on-hook |  | 5) Signalling sender |  |
|  | telephone off-hook |  | 6) Combined signalling sender and receiver | 0 |
|  | (b) trunk |  | 7) Timer supervising of a process | (ti) |
| - | (c) subscriber line |  | 8) Charging in progress |  |
|  | (d) switchboard |  | 9) Subscriber of terminal category | $\square$ |
|  | (e) other |  | 10) Uncertainty symbol | * |
| 3) Switching | (a) connected |  | 11) Switching module | 1 |
|  | (b) reserved | - - - - - | 12) Control element |  |
|  |  |  |  | CCITT-34100 |

FIGURE 31/Z. 103

Recommended symbols for the basic set of pictorial elements concepts

### 6.4 Special conventions and interpretations used in the state oriented extension of SDL/GR

A number of special conventions and interpretations have been defined in this section with regard to the state oriented extensions of $S D L / G R$. These include:

- The special interpretation required of process diagrams according to the so-called CARDINAL RULE (see § 6.2, rule 4).
- The unique positioning of pictorial elements (or pictorial elements and qualifying text) within a state picture that is required when using pictorial elements (see § 6.2 , rule 5 ).
- The special interpretation required for the variables represented by external pictorial elements and external qualifying text, as proxy variables for other variables associated with other processes.

Examples of the use of the basic set of pictorial elements


| No. | Pictorial element | Comment | Examples |
| :---: | :---: | :---: | :---: |
| 3. | Switching path <br> a) connected $\qquad$ <br> b) reserved | To show connectivity between terminal equipment and/or signalling devices involved in the process. | 3.1 Subscriber line connected to a dial-pulse digit receiver and a modem with a reserved path to a central processing unit (CPU) |
| 4. | Signalling receiver $\square$ | To specify a signal reception process, and to indicate the nature of the signals received, especially those crossing the functional block boundary. | 4.1 Multi-frequency code signalling receiver <br> 4.2 MFC/decadic signalling receiver |
| 5. | Signalling sender | To specify a signal sending process, and to indicate the nature of the signals sent, especially those required to cross the functional block boundary. | 5.1 Decadic signalling sender with a backward signal " $B 2$ " being sent |
| 6. | Combined signalling sender and receiver | This conveniently combines the functions of a signalling sender and signalling receiver. | 6.1 MFC sender-receiver |
| 7. | Timer supervising a process | Timers affect the subsequent behaviour of the process. <br> Note The related input symbol indicating timeout expiry, may be shown as $\overline{\mathbf{t}}_{\mathrm{i}}$. | 7.1 Timer $t_{3}$ is running <br> 7.2 Generic timer $t_{s}$ is running <br> where $s=1,2, \ldots n$ define different service tones. |




## Selection criteria for pictorial elements

## B. 1 General

The choice of symbols for PEs has been based upon the following considerations and general selection criteria, which should be consulted before developing additional PE symbols for wider applications of the SDL.

## B. 2 Typical readers

It is expected that the SDL diagrams using PEs will be read by both technical and non-technical people in the following contexts: marketing new facilities; specifying new facilities; developing hardware and software from a specification; project management; operation and maintenance of an exchange; traffic engineering; education and training courses in telephony. It is expected that SDL diagrams will serve as common documentation:
a) between Administrations and manufacturers,
b) between different departments within these organizations,
c) as telephone exchange documentation, and
d) in training manuals and textbooks.

It is not expected that SDL diagrams (as diagrams) will be directly read by machines. Instead it is expected that the SDL/PR form of the SDL (including PE information) will be read by machines which will draw diagrams (see b) and c) of § B.3).

## B. 3 Typical drawing methods

It is expected that SDL diagrams using PEs will usually be drawn by technical people, including draftsmen, either:
a) by hand, using a template as a drawing aid, and/or
b) displaying the diagram electronically on a graphics visual display unit, and/or
c) by using an electronically controlled plotter.

## B. 4 Methods of reproduction

The typical methods of reproduction are expected to be:
a) the dye-line or blue-print methods, as in conventional drafting;
b) photocopying by office machines, including photo-reduction;
c) photo-printing in general.

## B. 5 Ease of reproduction

In order to permit convenient reproduction of SDL diagrams using the dye-line or blue-print methods of reproduction as well as photocopying and photo-printing, PE symbols should consist of clear lines without shading.

## B. 6 . Ease of drawing

The following criteria reflect the assumption that the primary drawing technique will be to draw by hand using a template, and the secondary techniques will be displaying a diagram on an electronically controlled screen, and drawing the diagram with an electronically controlled pen:
a) each PE symbol should be easy to draw with pen or pencil, either free-hand or using a stencil;
b) all PE symbols should be drawn using the same thickness of lines;
c) PE symbols should be created by synthesis of very simple geometric lines and curves in order to permit easy electronic generation of PE symbols.

This is the most important consideration of all, since it is characteristic of SDL documentation that the readers are much greater in number than the drawers (or authors). This requirement is expressed by the following criteria concerning PE symbols:
a) Appropriateness - The shape of each symbol should be appropriate to the concept that the symbol represents.
b) Distinctiveness - When choosing a basic set of symbols, care should be taken to permit each symbol to be readily distinguishable from others in the set.
c) Affinity - The shapes of PEs representing different but related functions, e.g. receivers and senders, should be related in some obvious way.
d) Association of abbreviated text with symbols - In some cases it is expected that abbreviated text will be associated with a PE in order to indicate the class of PE; e.g. the letters MFC associated with a receiver symbol to indicate that multi-frequency coded signals are to be received. In these cases, the PEs should incorporate enclosed space to permit the use of a very small number of alphanumerical characters.
e) Limited set - The total number of symbols should be kept to a minimum in order to permit easy learning of the pictorial method.

## ANNEX C

(to Recommendation Z.103)
Recommended proportions for the basic sets of pictorial elements


CCITT-34110

## Recommendation Z. 104

## DATA IN SDL

## 1

## Introduction

This Recommendation defines the data concept in SDL; the SDL data terminology, the use of pre-defined data types, and the facility to define new data types.

The main occurrences of data in SDL are in data type definitions, expressions, the application of operators, variables, values, constants and literals.

## Data type definitions

Data in SDL is principally concerned with data types. A data type defines a set of values, a set of operators which can be applied to these values, and a set of axioms defining the behaviour when these operators are applied to the values. The values, operators and axioms collectively define the properties of data types. These properties are defined by data type definitions.

SDL allows the definition of any needed data type, including structuring mechanisms (composite types), subject only to the requirement that such a definition can be formally specified. By contrast for programming languages there are implementation considerations which require that the set of available data types and, in particular, the structuring mechanisms provided (array, structure, etc.) be limited.

## Expressions and operators

Expressions allow for the manipulation of values (by applying appropriate operators), to return new values.

## Variables

Variables are objects which can be associated with a value by explicit or implicit assignment. When the variable is accessed, the value is returned.

Values, constants and literals

All data types have at least one value. For most data types there are literal (syntactic) forms to denote the constant values of the data type (for example for Integers). Data types for which there are literals to denote values are said to have denotable constants. There may be more than one literal to denote the same constant value (for example 12 and $H^{\prime} \mathrm{C}$ both denote the same Integer constant), and the same literal denotation may be used for more than one data type. Some types do not have denotable constants. For example, values of the data type Stack can only be generated by the application of operators which return stack values.

In a specification language, it is essential to allow data types to be formally described in terms of their behaviour, rather than by composing them from provided primitives, as in a programming language. The latter approach invariably involves a particular implementation of the data type, and hence restricts the freedom available to the implementor to choose appropriate representations of the data type. The SDL approach allows any implementation providing that it is feasible and correct with respect to the SDL.

In SDL, all data types are abstract data types. Examples of these are given in § 5 where the pre-defined data types of the language are defined.

Although all data types are abstract, and the pre-defined data types may be re-defined by the user, some effort has been made in SDL to provide pre-defined data types which are familiar in both their behaviour and syntax. These are:

Array, Boolean, Character, Charstring, Duration, Integer, Natural, Powerset, PId, Real, String, Time and Timer.

Composite types can be formed by the use of Struct data types.

In SDL, data is modelled by a type algebra. A type algebra is a set of domains, a designated domain, and a set of functions mapping between the domains. Each domain is the collection of all the possible values for a data type. The designated domain is the data type currently being described. The functions represent the operations of the data type.

The domain and operations, together with the behaviour (specified by the axioms) of the data type, form the properties of the data type.

Introduction of a syntype creates a subset of the values of an already defined type. Introduction of a newtype creates a distinct new data type, with properties inherited from the parent, but with different identifiers for these properties. In the concrete syntax, these names need not be distinct, and this ambiguity must be resolved by context.

A generator type is an incomplete type description; before it assumes the status of a data type, it must be instantiated by providing this missing information.

The functions which map between the domains of a data type are normally partitioned into two classes. The generator functions, which map onto the designated domain, and so produce (possibly new) values of the data type. All other functions are semantic functions and ascribe meaning to the type by mapping onto other defined types. The semantic functions include the predicates which map onto the Boolean domain.

## 2 Common language model

### 2.1 General

In Recommendation Z.104, the concepts of variables, pre-defined data types, values, expressions and informal expressions are used. This Recommendation rigorously defines variables, pre-defined data types, values and expressions, and also extensions to the Recommendations Z.101, Z. 102 and Z. 103 which allow the introduction of new data types.

### 2.2 Abstract syntax

This abstract syntax extends that defined by Recommendations Z.101, Z.102 and Z.103.

## Data definition

A data definition is a data type definition or a synonym definition.

## System definition

A system definition may contain data definitions.

## Block definition

A block definition may contain data definitions.

## Internal part block definition

An internal part block definition may contain data type definitions.

## Channel substructure definition

A channel substructure definition may contain data definitions.

## Process definition

A process definition may contain data definitions and variable definitions.

## Procedure definition

A procedure definition may contain data definitions and variable definitions.

## Input node

A variable mentioned in an input node must be defined in a variable definition and must have the same data type as the corresponding data type in the signal definition.

A data type definition contains a type name and either a newtype description or a syntype description.

## Newtype description

A newtype description contains a possibly empty set of value names, a set of one more operator introductions and a possibly empty set of data type axioms.

All value names in the data type description must be unique within the data type.
All operator names in the data type description must be mutually exclusive.
All data type names in the same context must be unique.

## Operator introduction

An operator introduction either introduces one of the universal operators which it is permissible to introduce with any data type, or introduces an operator name together with the operator typing.

## Operator

An operator is either a universal operator with a data type identifier or is a user-defined operator identifier with a data type identifier. In either case the data type identifier allows the data type definition which defined the operator to be established.

## Operator typing

An operator typing contains the list of data type identifiers of the parameters to the operator and the data type identifier of the result of applying the operator.

At least one of the data type identities in the list, or the result, must be that of the data type being defined.
The result type must not be a syntype.

## Axioms

Axioms are statements of truth which hold under all conditions for the type being defined, and thus specify the behaviour of types.

## Assignment statement

An assignment statement contains an assignment operator, a variable identity and an expression. The assignment operator is either the universal operator for assign qualified with the data type identity of the data type of the variable or the user defined insert operator.

## Syntype description

A syntype description contains a syntype name, the parent data type identity and the set of value identities of the parent data type which are valid for the syn data type.

## Expression

An expression is either a primary, or an operation.

## Operation

An operation contains an operator and a list of one or more expressions. There are as many expressions contained in the operation as there are data types defined for the parameters of the operator.

Primary
A primary is one of the following:

- a synonym identity,
- a value identity,
- a variable identity, or
- a conditional expression.

A conditional expression is a Boolean expression, and a list of two expressions of the same data type.

## Variable definition

A variable definition consists of a variable name list and a data type identifier.

## Universal operation

A universal operator is either a variable operator or a comparator.
A variable operator is declare, assignment or access. Declare is used to declare variables; assignment is used for assigning to variables and access is used whenever a variable identity is interpreted as a value.

A comparator is either one of the ordering operators or an equality operator. An ordering operator is either less than or greater than.

All the universal operators include the data type to which they are relevant as a qualifier so that different data types introduce different operators. For example, the two data types square and cube introduce two operator identities for assign, square!assign and cube!assign.

For a data type D , the operator typing for comparators is:

## D, D - > Boolean

For a data type D , the assign operator requires a variable identity of data type D and value of data type D .

For a data type D , the access operator requires a variable identifier of data type D and delivers a value of data type D .

For a data type D , the declare operator requires a variable identifier.

## Synonym definition

A synonym definition contains a synonym name and a constant expression.

## Constant expression

A constant expression is either a constant value or an operation all of whose parameters are constant expressions.

## Constant value

A constant value is either a value identifier or a synonym identifier. A synonym may not be recursively defined.

### 2.3 Interpretation rules

### 2.3.1 Process

Instantiation of process takes place before the start node is interpreted, and causes a declare operation to be applied to every variable name which appears in a variable definition in the process definition. As a result of the declare operator, the variables declared become associations from variable identities to an initial value (which will be undefined value unless otherwise specified in the axioms for the data types of the variables). The variable identities declared when instantiating a process contain the variable name, the process instance identity and the data type identity from the variable definition.

### 2.3.2 Procedure start node

Calling a procedure causes variables defined within the procedure to be created for a procedure in a similar way to instantiating a process.

### 2.3.3 Process graph

The interpretation of an output node causes each of the expressions in the output node to be interpreted in the sequence specified, and the resulting values to be assigned to anonymous implicit variables which are associated with the signal. These variables are considered to be declared when the output node is interpreted. Each of these variables has the data type of syn data type associated with the corresponding position in the signal definitions. The values which are assigned to these variables are the values conveyed by the signal.

The interpretation of a decision node causes the expression contained in the decision node to be interpreted followed by the choosing of the arc which is associated with the value delivered by the expression.

## Create request

The interpretation of a create request node causes each of the expressions in the create request node to be interpreted in the sequence specified.

The instantiation of the process being created then takes place together with the declaration of the formal parameter of the process and the assignment of the corresponding resulting value of each expression in the create request node to each formal parameter. The created process then executes separately from (but concurrently with) other processes.

## Call node

A call node causes expressions used as formal parameters attributed with $I N$ to be interpreted before the interpretation of the start node of the procedure. Each of the expressions assigns its value to the corresponding actual parameter.

### 2.3.4 Procedure

A formal parameter attributed with $I N / O U T$ is interpreted as the variable identifier of the corresponding actual parameter in the context of the procedure call. A formal parameter attributed with SIGNAL is interpreted as the signal identifier of the corresponding actual parameter in the context of the procedure call.

### 2.3.5 Assignment statement

The assignment statement is interpreted as combining the old value of the variable with the value of an expression and binding the variable identity to this new value.

The assignment operator determines the rules for combining the old value of the variable with the value of the expression. These rules are determined by the use of the assignment operator in data type axioms of the data type. If the assignment operator is the universal operator for assignment, then the variable is bound to the value of the expression.

The value of the expression must be one of the values of the data type of the variable of the assignment operator. For the universal operator for assignment the data type of the parameter is that of the variable.

### 2.3.6 Expression and primary

An expression is interpreted as the primary which forms the expression. The primary is either an operation, a synonym, a value identifier, or a variable identifier, and is so interpreted.

### 2.3.6.1 Operation

An operation is interpreted as an application of the operator to the list of values obtained by interpreting the list of expressions. The interpretation of the operation is determined by the use of the operator in the data type axioms of the data type.

### 2.3.6.2 Synonym identifier

A synonym identifier is interpreted as the constant expression defined in the synonym definition. The constant expression is interpreted in the same way as an expression.

### 2.3.6.3 Value identifier

A value identifier is interpreted as the value it denotes.
The semantics of the value which a value identifier denotes is determined by the use of the value identifier in the data type axioms of the data type.

### 2.3.6.4 Variable identifier

A variable identifier is interpreted in one of the two ways depending on context. Within an expression a variable identifier is interpreted as an access. In the context of an assignment statement a variable identifier is interpreted as a variable, which is the binding of the variable identifier to a value. Access to a variable is intepreted as the value to which the variable is bound, except that access to the undefined value is interpreted and an error.

A conditional expression is interpreted as the first or second expression in the list, depending on whether interpretation of the Boolean expression yields true or false.

### 2.3.7 Data type definitions

These are not interpreted.

## 3

SDL/GR

The standard SDL specification of the behaviour of tasks, decisions, etc. (i.e. the internal structure of these nodes) is the SDL/PR form. Thus there is no specific graphic syntax for data.

Where the data definitions (for data types, variables or synonyms) are included, they should be defined with or referenced by the diagram which includes them.

## 4 SDL/PR

### 4.1 Addition to syntax

Data definitions are added to the syntax as defined in Recommendations Z.101, Z. 102 and Z. 103
Data definitions may appear where a signal definition appears in a system definition, block definition, block substructure definition or a channel substructure definition. A data definition may also appear where a variable definition may appear in a process definition where a procedure variable definition may appear in a procedure definition.

## SYSTEM DEFINITION




BLOCK SUBSTRUCTURE DEFINITION


## CHANNEL SUBSTRUCTURE DEFINITION



PROCESS DEFINITION


The syntax of data type is extended to include user defined data type identifiers.
The syntax for assignment statements and expressions is given. (Note expressions and assignment statements are mentioned in Recommendation Z.101 but not defined.)

### 4.2 Data definition

### 4.2.1 Syntax

DATA DEFINITION


### 4.2.2 Semantics

A data definition is used to introduce the names and properties of data types, data type generators or synonyms.

### 4.2.3 Relationship to SDL Abstract Syntax

A data definition in SDL/PR represents a data definition in the abstract syntax. If the data definition is a data type generator then there is no direct correspondence with abstract syntax, as the data type generator serves only to define text which is considered to be textually expanded on generator instantiation.

### 4.3 Data type definition

### 4.3.1 Syntax




CONSTANTS

value set


## CONSTANT



### 4.3.2 Semantics

The name given in a data type definition is a data type name.

### 4.3.2.1 NEWTYPE

## A NEWTYPE data type definition introduces a new data type.

If no inheritance rule is specified then the new data type is not based on any other type. The type properties are used to introduce any literals for that type, the operators applicable to the type and (optionally) the properties of the type by stating axioms which hold true for the type.

A new type may be based on another type by using NEWTYPE in combination with inheritance rules In this case, the value set of the new data type is disjoint from the value set of the parent type. Although the values and operators of the new data type are distinct from those of the parent data type, the literals and names of the operators for the new type will be overloaded, that is they will be the same literals and names as for the parent type and whether a literal or name is appropriate to the new type or parent data type will have to be decided either by qualification or by context. If the binding of a literal or operator name to a type cannot be determined then the SDL specification is ambiguous and hence invalid. When $A L L$ is given for an inheritance rule then all the operator names are overloaded for the new data type. Otherwise the operator names specified in the inheritance rule must be operator names of the parent type and these names are defined for the new type. The axiom set and literal set of the parent data type is inherited.

As well as the inherited literals, operator names and axioms, a new data type may have additional literals, operators and axioms specified as type properties after the keyword ADDING. These literals, operator names and axioms must not conflict with those inherited.

A data definition of the form:

```
NEWTYPE X/* details */
    CONSTANTS /* constant list */
    END X;
```

is equivalent to

```
NEWTYPE Anon /* details */
    END Anon;
```

followed by
SYNTYPE X $=$ Anon CONSTANTS /* constant list */ END X;

The use of a constant restriction on a NEWTYPE implicitly declares an anonymous NEWTYPE (Anon above) without that restriction, which is then used as the parent of a SYNTYPE with the constant restriction. To enforce the anonymity, the parent name is stated to be distinct from all other names denoted in the SDL specification outside of the particular implicit declaration.

A data type may also be defined to have a subset of the values of the parent data type by using SYNTYPE. In this case the value set is either specified after the keyword CONSTANTS, or all the values of the parent data type have corresponding values in the SYNTYPE. Variables declared with a SYNTYPE may only be assigned the values specified.

Accessing a variable with a SYNTYPE yields a value of the parent data type. These operations of declare, assignment and access are the only operations allowed for SYNTYPES.

The values specified for a SYNTYPE data type must all be values of the parent data type. The parent of a Syntype is the second type nominated in the Syntype definition provided that Type is a Newtype. Otherwise the parent is the parent of the nominated type.

### 4.3.2.3 Generator instantiation

A generator instantiation is equivalent to the text of the generator with the formal parameters textually replaced by the actual parameters. Wherever the generator name is used in the text of the generator, it is replaced by the name of the data type or generator calling the generator instantiation. The equivalent text must complete a valid NEWTYPE data type definition. This data type definition formed by the textual expansion then defines the properties of the data type name.

### 4.3.2.4 Struct

A data type definition which includes a Struct implies data types for each field name. For a given structure type S , for each field name $F_{i}$ and corresponding type identifier $T_{i}$, the following axioms are implicitly introduced (subject to strengthening; see below):

- the single axiom : extract!(insert!(S,Fi,I), Fi) $=\mathrm{I}$
- the axiom set : extract!(insert!(S,Fi,I)',Fj)
$=\operatorname{Extract}(\mathrm{S}, \mathrm{Fj})$;
/* for all distinct $\mathrm{Fi}, \mathrm{Fj}$ */
Where there are N field names in a structure, there will be $\mathrm{N}^{*} \mathrm{~N}$ axioms of this form implicitly introduced. To guarantee resolution of ambiguity, SDL requires that field names within a given structure be unique.

Associated with the structure S is a set of types, one for each field, with type name $\mathrm{S}!\mathrm{Fi}$, the single literal Fi, and no other properties. This type becomes the carrier for the field name used in Insert! and Extract! operations.

The effect of a Struct definition is to create a (programming-language like) structure or record, although the definition may include additional axioms to strengthen the behaviour of the type. Where additional axioms explicitly introduced by the user conflict with the implicit default axiom set for that Struct, the inconsistency is resolved by discarding implicit axioms. Introduction of explicit axioms into a Struct requires great care.

### 4.3.3 Relationship to abstract syntax

A data type definition represents a data type definition in the abstract syntax. The type name represents the type name in the abstract syntax.

### 4.3.3.1 NEWTYPE

The keywords NEWTYPE and END embrace the abstract syntax concept of a data type description. The value name set, operator introductions and type axiom set in the abstract syntax are represented as follows:
a) Value name set

The set of literals given by the literals in the type properties combined with the set of literals for the parent data type if INHERITS is specified.
b) Operator introduction set

The set of operators given by the operators in the type properties combined with the set of operators of the parent data type if INHERITS is specified.
c) Type axiom set

The set of axioms (if any) given by the axioms in the data type properties combined with the set of axioms of the parent data type if INHERITS is specified. If the axiom set is omitted, or is incomplete, then at least some operations can only be interpreted informally.

### 4.3.3.2 SYNTYPE

The keywords SYNTYPE and END embrace the abstract syntax concept of a syntype description. The parent type identifier represents the parent data type identifier in the abstract syntax. The value set represents the value set in the abstract syntax.

### 4.3.3.3 Generator instantiation

A generator instantiation denotes the text which would be obtained by textually expanding the generator as in § 4.3.2.3 so that it has the same relationship with the abstract syntax as the equivalent text.

### 4.3.3.4 STRUCT

A Struct denotes the text obtained by explicitly nominating all relevant properties and thus (as for a generator) has the same relationship to the abstract syntax as the text so denoted.

### 4.4 LITERALS

### 4.4.1 Syntax



LITERAL


PREDEFINED LITERAL


CCITT-78B00

## REAL LITERAL



## BOOLEAN LITERAL



### 4.4.2 Semantics

The literals which are used to denote the values of a data type are either predefined (for predefined data types or data types based on predefined data types) or are introduced by the list of denotations for the literals of a data type after the keyword LITERALS. Where a type includes the Ordering! operations, the literals should be conventionally nominated in ascending order.

### 4.4.3 Relationship with abstract syntax

The literal names introduced by the literals part of data type properties represents the value names of a data type description in the abstract syntax.

## 4.5 <br> Operators

### 4.5.1 Syntax

## OPERATORS



## INFIX OPERATOR



### 4.5.2 Semantics

The operators of data type properties introduce the names for operators and the parameterization of these operators. The parameterization determines the number of parameters required and the data type of each parameter and also the data type of any values returned.

### 4.5.2.1 Operator names

The ordering operators are specified by including Ordering! in the operators. This is shorthand notation for introducing the following operators for a data type D.
" < " :
D, D $->$ Boolean
$">"$ :
D, D -> Boolean
" < = ":
D, D $->$ Boolean
" $>=$ ": D, D $->$ Boolean

The names of infix operators e.g. + , AND, OR, are enclosed in quotes in the operators. They may be used as prefix operators by using this quoted form, that is:

$$
"+"(a, 2)
$$

is equivalent to $\mathrm{a}+2$.
An operator name may be optionally followed by an exclamation mark, which denotes that the operator identity may only be referred to directly in data type definitions. The exclamation mark forms part of the name of the operator and so must always be given when the operator is used.

The names Assign!, Declare!, Access!, " $="$ and "/ =" are defined implicitly as operators for all data types with the implied typing for a data type D .

```
Assign! : \(\mathrm{D}^{\prime *}, \mathrm{D}->\)
Declare! : \(\mathrm{D}^{\prime *}->\);
Access! : \(\mathrm{D}^{\prime}->\);
\("=" \quad: \mathrm{D}, \mathrm{D}->\) Boolean;
"/=" : \(\mathrm{D}^{\prime}, \mathrm{D}->\) Boolean;
```

The Assign operator is the infix operator, ":=". There is no Declare operator as its application is implied from declarations. The Access operator is implied whenever a variable is mentioned in a context which requires a value. The equals and not equals operators are the infix operators " $=$ " and "/ =" respectively.

### 4.5.2.2 Operator typing

The list of data type identifiers after the colon and before the symbol $(->)$ is called an operator type list. This operator type list specifies the data types of values which the operator requires. If one or more data type identifiers has a prime attribute, then the operator is an active operator otherwise it is a passive operator. An active operator can change the values associated with variables, whereas a passive operator is purely functional and so cannot change the values associated with variables.

For a passive operator all type identities in the type list specify that actual parameters of the operator have to be interpreted as expressions. Each of those expressions must yield a value, which is a member of the set of values of the data type of the corresponding position in the data type list.

For a passive operator there must be a data type identifier after the symbol ( $->$ ). This data type identifier specifies that the operator when applied, will yield a value of this data type. For an active operator some of the data type identities in the operator type list are followed by primes (').

A prime specifies that the operator requires a variable of the given data type as a parameter, and the value associated with the variable may be changed. No two data type identifiers may be followed by the same number of primes in the input data type list.

The number of primes distinguishes one primed parameter from another when an active operation is used with priming to denote the value associated with a variable given as a parameter (this is permissible only in axioms). For example:

OPERATORS SwapAndAdd: Int', Int" - > int
/* fragment of data type definition */
AXIOM SwapAndAdd $(\mathrm{a}, \mathrm{b})^{\prime}=\mathrm{b}$;
/* axiom stating the first parameter receives the value of the second parameter */

```
SwapAndAdd (a,b)" = a;
    /* axiom for second parameter */
SwapAndAdd (a,b) = a +b;
    /* result axiom */
```

If a primed parameter is followed by an asterisk, then the initial value of the variable is not accessed when the operation is used. (Note that the axioms must be consistent with this, otherwise the SDL specification is invalid.)

If the data type identifier after the symbol $(->)$ is omitted for an active operator, the operator may not be used within an expression. There may be both primed and unprimed parameters in an input data type list.

There is syntactic ambiguity between a data type name followed by a quoted character string in a name string, and a primed data type identifier in a data type list. These ambiguities arise when a prime after a type name in a type list is followed by a prime, a comma or a minus sign (part of $->$ ). In all cases the prime is taken as priming of the data type identifier and not as starting a quoted character string.

### 4.5.2.3 Insert! and Extract! operators

To allow the axiomatic definition of arrays and structures, there are two predefined operator names, which have a special denotation outside data type definitions. These operators are Insert! and Extract!. Insert! is an active operator and must be defined with the data type identities such that the first data type is primed and the other types are unprimed.

To apply Insert! outside data type definitions, the first parameter (which must be a variable) is written, followed by an open parenthesis, all the remaining parameters except the last, then a closing parenthesis and ": =", and finally the last parameter.

Thus with A a variable the data type of which has Insert! defined and i1, i2 and e expressions approriate to Insert! for this data type.

Insert!(A, i1, i2, e)
is written as

$$
\mathrm{A}(\mathrm{i} 1, \mathrm{i} 2):=\mathrm{e}
$$

Since Insert! can be defined for more than one data type; the appropriate Insert! is determined from the type of the variable. Insert! must be defined with at least two parameters and must return the same data type as the first parameter.

Extract! is a passive operator which requires a variable as the first parameter for semantic reasons. To apply Extract! the first parameter is written followed by all the other parameters in parenthesis.

Thus,
Extract!(A, i1, i2)
is written as
A(i1, i2)
The application of Extract ! is determined by the type of the variable.

### 4.5.3 Relationship to abstract syntax

For a passive operator an operator name or infix operator represents an operator name in the abstract syntax. For a passive operator the input type list represents the list of type identities of parameters in the abstract syntax. The data type identifier after the symbol $(->)$ represents the data type identity of the result of applying the operator.

An active operator is related to the abstract syntax by re-writing into passive operators. This also defines the ordering behaviour of the operation. For each primed parameter there is an implicit passive operator which returns the value required by the axiom set. For each primed parameter without an asterisk there is an implicit variable in each process instance using the operator with the same data type as the parameter which receives the initial value of the parameter.

The list of data type identities of parameters in the abstract syntax for each implicit passive operator is represented by the input data type list ignoring any asterisked parameters. There are as many implicit passive operators as there are primed parameters in the input data type list and each primed parameter data type is used as the data type identity of the result of applying one of these operators. For example:

## OPERATORS

complex: Integer', Integer", Integer, Integer"'" * > Bool
/* swaps first two parameters, puts the sum of the first three parameters in the fourth parameter and returns true if the second and third parameters were equal */

## AXIOMS

complex $(\mathrm{a}, \mathrm{b}, \mathrm{c}, \mathrm{d})^{\prime}=\mathrm{b}$;
complex (a,b,c,d)" $=\mathrm{a}$;
complex ( $\mathrm{a}, \mathrm{b}, \mathrm{c}, \mathrm{d})^{\prime \prime \prime}=\mathrm{a}+\mathrm{b}+\mathrm{c}$;
complex ( $\mathrm{a}, \mathrm{b}, \mathrm{c}, \mathrm{d}$ ) $=(\mathrm{b}+\mathrm{c})$;
$/$ see § 4.9.2 for the use of primes in axioms */.
The implicit operators are:
implied1!: Integer, Integer, Integer $->$ Integer
implied2!: Integer, Integer, Integer $->$ Integer implied3!: Integer, Integer, Integer $->$ Integer
implied4!: Integer, Integer, Integer $->$ Boolean

If the implied variables are V 1 , and V 2 , an application of complex in a statement is equivalent to:
$\mathrm{V} 1:=\mathrm{a} ; \mathrm{V} 2:=\mathbf{b}$;
followed by the statement, but with V1 substituted for $a$, V2 substituted for $b$, and implied4! substituted for complex, followed by
$\mathrm{a}:=$ implied1! (V1,V2,c);
$\mathrm{b}:=$ implied $2!(\mathrm{V} 1, \mathrm{~V} 2, \mathrm{c})$;
$\mathrm{d}:=$ implied3! (V1,V2,c);
Where more than one active operator is present, in a statement, they are substituted in the order in which they would be interpreted.

### 4.6 Axioms

4.6.1 Syntax

## AXIOMS



## AXIOM



QUANTIFICATION


### 4.6.2 Semantics

The axioms are a set of Boolean expressions which hold true for all values of the variables in the axioms.
Within an axiom a "variable" is never the name for a process or procedure variable, which has a value associated with it, but is used to denote that all values of a specific type may be substituted for the variable and the axiom is still true. When considering this substitution a given variable name always represents the same value in one axiom. For example in:

OPERATORS even: Integer $->$ Boolean
AXIOMS even (0) = True; $\quad / *$ axiom 1 */
even $(1)=$ NOT even $(i+1) ; /^{*}$ axiom $2^{*} /$
The axiom 2 must hold for $\mathrm{i}=2, \mathrm{i}=3, \mathrm{i}=4$ etc., that is,
even $(2)=$ NOT even $(2+1)$
even (3) $=$ NOT even $(3+1)$
even $(4)=$ NOT even $(4+1)$

Usually the data type of a variable in an axiom can be determined by context e.g., in the above example it is required to be of data type int by the operator syntax.

Sometimes because of overloading of names and symbols (such as "+") in SDL, it is not possible to determine the data type of an axiom variable by context, so that the optional quantification is needed. Quantification forces a variable to be of particular type. It the use of a variable within one axiom is ambiguous or inconsistent then the SDL/PR is invalid.

Quantification also allows a variable name to represent the same substitution in more than one axiom.
The variable names chosen for variables in axioms must be distinct from literals appropriate to the context where the variable is used.

Since the operators " $=$ " and " $/=$ " are implied for all data types, the following axioms are always implied:

```
\(" /="(a, b)=\operatorname{NOT}("="(a, b))\)
\("="(a, a)\);
\("="(a, b)\) AND " = " \((b, c)=>"="(a, c)\);
\("="(a, b)=>"="(b, a) ;\)
```

Whenever Ordering! is specified, the following axioms are implied:
"<" $(\mathrm{a}, \mathrm{b})=>$ NOT " $>$ " $(\mathrm{a}, \mathrm{b})$;
">" $(\mathrm{a}, \mathrm{b})=>$ NOT " $<"(\mathrm{a}, \mathrm{b})$;
$"<"(a, b)$ AND " <" $(b, c)=>"<"(a, c)$;
NOT " <" $(a, a)$;
$"<="(\mathrm{a}, \mathrm{b})=>"<"(\mathrm{a}, \mathrm{b})$ OR "=" $(\mathrm{a}, \mathrm{b})$
$">="(\mathrm{a}, \mathrm{b})=>$ ">" $(\mathrm{a}, \mathrm{b})$ OR"=" $(\mathrm{a}, \mathrm{b})$

### 4.6.3 Relationship to abstract syntax

The axioms represent the data type axioms in the abstract syntax. Each axiom represents an axiom in the abstract syntax.

Quantification represents quantification in the abstract syntax, except that there is implies quantification in the concrete syntax for all axiom variables whose data type is determined by context.

### 4.7 Expressions

### 4.7.1 Syntax

EXPRESSION


OPERAND 0



OPERAND 5


### 4.7.2 Semantics

An expression is either a primary or is the application of a number of "infix" operators.
The order of application of operators is determined by their appearance in the syntax in a similar way to programming languages such as CHILL (see Recommendation Z.200). However, SDL also allows the Boolean implication operator $(=>)$, which has lower precedence than any other operator. This has the value FALSE for Boolean operands if the left hand operand is TRUE and the right hand operand is FALSE. Otherwise for Boolean operands the implies operation has the value TRUE.

Normally all operators will have the same properties and validity as defined in programming languages, but it should be noted that in SDL the user may define new meanings for these operators by including them in data type definitions. Nevertheless, the precedence of "infix" operators may not be changed.

The value yielded by a valid operation is determined by the axioms in data type definitions.

### 4.7.3 Relationship to abstract syntax

An expression represents an expression in the abstract syntax.
An "infix" operator can be overloaded and may represent any one of a number of operators in the abstract syntax. The overloading is resolved in two ways: either by the number and type of parameters or, in the case where the parameters themselves are overloaded, by the data type required in the context in which the operation is used.

### 4.8 Primary

### 4.8.1 Syntax

PRIMARY


### 4.8.2 Semantics

A primary is a variable identity or a literal or a synonym identity or a conditional expression or an operation or a bracketed expression.

### 4.8.3 Relationship to abstract syntax

A variable identity or literal or synonym identity or conditional expression or bracketed expression represent a variable identity access, value identity, synonym identity, conditional expression or expression respectively in the abstract syntax.

When a variable identity is referred to in an axiom it represents an axiomatic variable rather than a reference to an access to a variable declared for a process or procedure. The data type of an axiomatic variable is determined by context.

## OPERATION



### 4.9.2 Semantics

An operation is the application of an operator defined in a type definition. The number and type of the expressions used as actual parameters must be consistent with the definition of the operator identity. These parameters may be used to determine which operator is being applied if the operator name is overloaded.

If the operator is being applied in an axiom then if the name is defined with an exclamation mark then this exclamation mark must be repeated in the axioms.

An operator defined with an exclamation mark may not be used outside a type definition.
The primes after the closing bracket of the operator may only be used in an axiom and denote that the operation has the resultant value of the parameter defined with that number of primes. For example:

## OPERATORS

example: $\mathrm{t}^{\prime}, \mathrm{t} 2^{\prime \prime}->$

## AXIOMS

example: $(\mathrm{v} 1, \mathrm{v} 2)^{\prime \prime}=\mathrm{v} 1$
/*value of v1 put in v2 */
When the typing of a parameter of an operator is specified with primes, the actual parameter must be a variable, except in the context of an axiom.

### 4.9.3 Relationship to abstract syntax

A passive operator identifier represents an operator in the abstract syntax. For a passive operation, the expression list represents the expression list in the abstract syntax for that operation.

An active operation represents assignment to implicit variables which are then used as arguments to implicit passive operations, whose values are assigned back into variables given as actual parameters (see § 4.5.3). Within an axiom an active operation represents an application of the appropriate implicit passive operation determined by the number of primes appended to the operation.

### 4.10.1 Syntax

## CONDITIONAL EXPRESSION



### 4.10.2 Semantics

The conditional expression is interpreted by interpreting the expression after THEN if the Boolean expression is true, and yields the value of the expression after ELSE otherwise.

Within an axiom each branch of the conditional expression need only be valid for the conditions under which it is selected. For example since $\log (x)$ is not defined for negative number, in

IF r > 0 THEN $\log (\mathrm{r})$ ELSE 0.0 FI
if does not matter that for $r<=0, \log (r)$ is undefined.

### 4.10.3 Relationships to abstract syntax

A conditional expression represents a conditional expression in the abstract syntax.

### 4.11 Assignment statement

### 4.11.1 Syntax

## ASSIGNMENT STATEMENT



### 4.11.2 Semantics

An assignment statement allows a value to be associated with a variable.
The value yielded by the expression on the right hand side is assigned to the variable or an element of the variable on the left hand side.

### 4.11.3 Relationship to abstract syntax

An assignment statement represents the application of either an Assign! operator or as an Insert! operator.
There is a mapping between the syntax of an assignment and the application of the appropriate operator.
Where no brackets are used on the left hand side of an assignment then the assignment represents the use of Assign!, such that

V : = e represents Assign!(V,e)
When a single pair of brackets is used, such an assignment represents Insert! such that
$\mathrm{a}(\mathrm{i}):=\mathrm{e}$ represents Insert! (a,i,e)
and
$\mathrm{a}(\mathrm{i}, \mathrm{j}):=\mathrm{e}$ represents Insert! ( $\mathrm{a}, \mathrm{i}, \mathrm{j}, \mathrm{e}$ )
When multiple brackets are used an assignment is represented be recursive substitution such that
$\mathrm{a}(\mathrm{i})(\mathrm{j}):=\mathrm{e}$
represents
$\mathrm{vi}:=\mathrm{a}(\mathrm{i}) ;$
Insert!(vi,j, e);
$\mathrm{a}(\mathrm{i}):=\mathrm{vi}$;
where vi is an implicit variable whose type is the same as a(i). The implied Insert! operations are active operations, which are represented in the abstract syntax in the normal way for active operators (see § 4.9.3).

### 4.12 Synonym definition

4.12.1 Syntax

## SYNONYM DEFINITION



### 4.12.2 Semantics

The synonym is equivalent to the constant expression. If the type of the expression cannot be determined by either the constant or the context of the synonym definition then a type must be specified otherwise the value and type of the constant expression and hence the value of the synonym), is determined by the context in which the synonym definition appears.

### 4.12.3 Relationship to abstract syntax

A synonym represents a synonym definition in the abstract syntax. If the data type is omitted, then it is implied by context.

### 4.13 Data type generator

### 4.13.1 Syntax

### 4.13.2 Semantics

The name given in a Data Type Generator is a Data Type Generator name. The properties supplied in a generator form a partial specification of a data type. When a generator is used in a Type Definition or another Data Type Generator, the parameters to the generator are textually substituted in the generator definition and
(together with any properties added in a Type Definition) then must form a complete Type Definition or another Data Type Generator. Where a Data Type Generator is defined in terms of a generator instantiation, the generator parameters may have the same name as those supplied to the instantiation. Such a generator is a Partial Instantiation. For example:

GENERATOR Stack (TYPE Component, CONSTANT Maxsize)
/* details */

END Stack;
GENERATOR IStack(CONSTANT Max) Stack(Integer, Max)
END IStack;
/* A stack of integers, maximum size not specified */

### 4.13.3 Relationship to abstract syntax

The Data Type Generator has no counterpart in the abstract syntax. Usage of a generator Instantiation in a Data Type Definition will denote the text formed by parametric substitution.

## DATA TYPE GENERATOR



GENERATOR INSTANTIATION


## Integer

NEWTYPE Integer
/* Literals according to integer literal syntax */

## OPERATORS

"+": Integer, Integer $->$ Integer;
" - ": Integer, Integer $->$ Integer;
" - ": Integer, Integer $->$ Integer;
"/" Integer, Integer -> Integer;
Float: Integer $->$ Real;
Fix: Real $->$ Integer;

## AXIOMS

/* inherited from mathematical integers, adding: */
Fix(Float(r)) $=r$;
$\mathrm{r}-1<\operatorname{Float}(\operatorname{Fix}(\mathrm{r}))<=\mathrm{r}$;
$\mathrm{i} / \mathrm{j}=\operatorname{Fix}(\operatorname{Float}(\mathrm{i}) / \operatorname{Float}(\mathrm{j}))$
END Integer;

2 Real

NEWTYPE Real
/* Literals of the form specified in 'real literal' */
OPERATORS
"-": Real, Real $->$ Real;
"+" Real, Real $->$ Real;
"*": Real, Real -> Real;
"/": Real, Real - > Real;
"-": Real -> Real;
/* Axioms are inherited from the mathematical reals; this work needs further study to be more formally specified here */

END Real;

Array
GENERATOR Array(TypeIndex, TYPEItem);
OPERATORS
Insert!: Array', Index, Item ->;
Extract!: Array, Index $->$ Item;

## AXIOMS

Extract! (Declare!(V)', ]) = Error!;
Extract!(Insert!(A, IPos, It), EPos =
If Epos $=$ Ipos Then It Else Extract(A, EPos) FI;
End Array;

Boolean

NEWTYPE Boolean;
LITERALS True, False;
OPERATORS
"NOT": Boolean -' Boolean;
"AND": Boolean, Boolean - > Boolean;
"OR": Boolean, Boolean $->$ Boolean;
$"="$ : Boolean, Boolean $->$ Boolean;

AXIOMS
"NOT" (True) $=$ False;
"NOT"(False) = True;
"AND" $(\mathrm{A}, \mathrm{B})=$ If A $=$ False Then False Else B;
"OR" $(A, B)=$ If $A$ Then True Else B;
$"=>"(A, B)=$ If $A=$ True And B $=$ False Then False Else True;
END Boolean;

## NEWTYPE Character

LITERALS/* character strings of length 1 , where the characters are those of the CCITT alphabet number 5 */;

OPERATORS
Ordering!;
END Character;

Natural
SYNTYPE Natural Integer Constants $>=0$ END Natural;

## Powerset

GENERATOR Powerset(TYPE Item);
LITERALS Empty;
OPERATORS
"IN": Item, Powerset $->$ Boolean;
Incl: Item, Powerset' $->$;
Del: Item, Powerset' $->$;
Ordering!;
AXIOMS;
Declare(v) ${ }^{\prime}=$ Empty;
I IN Empty = False;
I IN Incl(12, S) $=$ IF I $=12$ THEN True ELSE I IN S FI;
$\operatorname{Del}(\mathrm{I}, \operatorname{Incl}(\mathrm{I} 2, \mathrm{~S}))=\mathrm{IF} \mathrm{I}=\mathrm{I} 2 \operatorname{THEN} \operatorname{Del}(\mathrm{I}, \mathrm{S}) \operatorname{ELSE} \operatorname{Incl}(\mathrm{I} 2, \operatorname{Del}(\mathrm{I}, \mathrm{S})) \mathrm{FI}$;
For all S1, S2 in powerset (for all I in Item (S1 < S2 = (I IN S1 = > I IN S2)) ;
$\operatorname{NOT}(\mathrm{I}$ in S$)=>\operatorname{Del}(\mathrm{I}, \mathrm{S})=\mathrm{S}$;
END Powerset;

PId
NEWTYPE PId
LITERALS Null;

## OPERATORS

Create! : - > PId;

## AXIOMS;

Declare!(v)' = Null;
Create! / = Create!;
/* A weak way of stating that all Creates yield unique values */
Create! / = Null;
/* PId values are returned by the interpretation of a create request node (they are denoted as being generated by the Create! function above). Every create request interpretation generates a unique PId value which is not Null. Every process instance implicitly declares three PId variables, named "Parent", "Self" and "Offspring".
Interpretation of a Create request node generates a new and unique PId value, and assigns it to the Offspring for the creating task. The Self identifier of the created task is assigned this same value, while Parent of the created task is assigned the value of self of the creator. The length of Offspring in the created task is set to zero.

```
*/ END PId;
```

GENERATOR String (TYPE Item);
/* Literals specified by Charstring literals, */
/* only if generator is instantiated with Character */

## OPERATORS

Declare!(v)' : - > String;
"//" : String, String $->$ String;
Length : String $->$ Natural;
First : String $->$ Item;
Last : String - > Item;
Extract! : String, Natural $->$ Item;
Insert : String', Natural, String $->$;
Insert! : String', Natural, Item $->$;
AXIOMS
Length(Declare!(v) $\left.)^{\prime}\right)=0$; Length (S1 // S2) $=$ Length(S1) + Length(S2); First(S1) $=$ Extract!(S1, 1); Last(S1) $=$ Extract!(S1, Length(S1)); Extract!(Insert(S1,I,S2),j) = IF $\mathrm{j}<1$ THEN Error! ELSE

IF $\mathbf{j}<=$ I THEN Extract!(S1,j) ELSE IF $\mathbf{j}<=$ Length(S2) + I THEN Extract!(S2,j-I)) ELSE IF $\mathrm{j}<=$ Length (S1) + Length(S2) THEN

Extract!(S1,J - Length(S2)) ELSE Error! FI
FI
FI FI;
S1 // S2 = Insert(S1, Length(S1), S2);
Extract!(Insert!(S1, I, It)', J) =
IF I = J Then It Else Extract!(S1, J) FI;
END String;

Time

NEWTYPE Time Inherits Real

## ADDING

Operators
Now: - > Time /* the 'real' time */;

END Time;

## Duration

NEWTYPE Duration Inherits Real ("+", "-", "*","/")
ADDING
Operators

$$
\begin{aligned}
& "+": \text { Time, Duration }->\text { Time; } \\
& "+": \text { Duration, Time }->\text { Time; } \\
& "-" \text { Time, Duration }->\text { Time; }
\end{aligned}
$$

CONSTANTS $>=0.0$
END Duration;

## NEWTYPE Timer

## OPERATORS

Set: Time, Timer ${ }^{*}$ - > ;
Reset: Timer' $->$;
Active: Timer $->$ Boolean;

## AXIOMS

Active $\left(\operatorname{Set}(\mathrm{Tm}, \mathrm{Tmr})^{\prime}\right)=\operatorname{Tm}>$ Now ();
Active $(\operatorname{Reset}(T \mathrm{Tm})$ ) $=$ False;
/* Note that an active timer sends a signal to the process when it becomes inactive. This signal is named with the same name as the timer variable in the Set call */

END Timer;

## Charstring

NEWTYPE Charstring String (Character)
Adding LITERALS /* character string literals */
END Charstring;


[^0]:    1) The formal definition of SDL will be obtainable from the International Telecommunication Union, General Secretariat - Sales Section, Place des Nations, CH-1211 Genève 20 (Switzerland).
    2) The SDL course will be available through the International Sharing System for Training, ITU Secretary General Technical Cooperation Department, Training Division, Place des Nations, CH-1211 Genève 20 (Switzerland).
[^1]:    Syntax diagrams for channel substructure

